

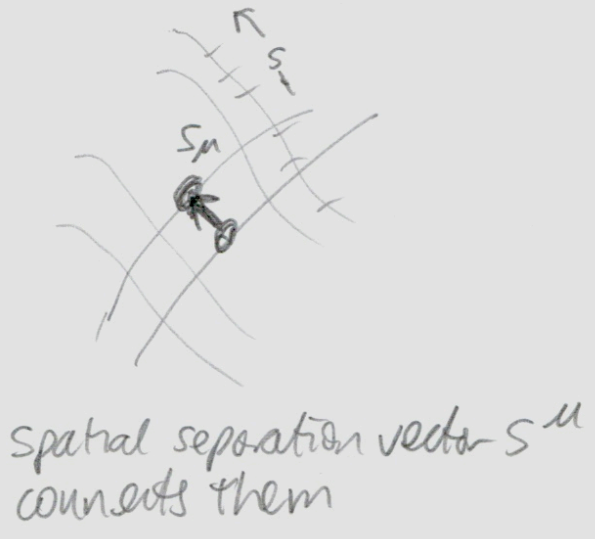
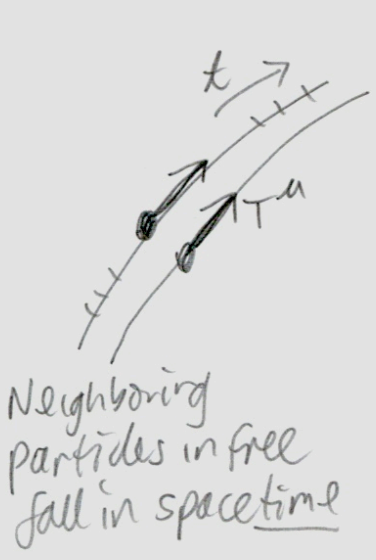
# General Relativity

$$ds^2 = g_{\mu\nu} dx^\mu dx^\nu$$

special  
relativity:  
g's must  
be geometrically  
flat

General relativity:  
Allow non-flat g's  
Gravity resides in  
non-flatness.  
Special slices also  
adopt non-Euclidean  
geometry

# Tidal Acceleration



$$\left[ \frac{D^2}{dt^2} S^\mu = R^\mu_{\nu\rho\sigma} T^\nu T^\rho S^\sigma \right]$$

↑  
Riemann curvature tensor

$\frac{D}{dt}$  = "directional covariant derivative" ... same derivative used in geodesic equation

Acting on a vector  $v^\mu$

$$\frac{Dv^\mu}{dt} = \frac{dv^\mu}{dt} + \Gamma^\mu_{\sigma\rho} \frac{dx^\sigma}{dt} v^\rho$$

← looks like ordinary differentiation if we pick a coordinate system in which  $\Gamma^\mu_{\sigma\rho} = 0$

Flatness  $\implies$  No tidal accelerations

$R^{\mu}_{\nu\rho\sigma} = 0 \implies \frac{D^2}{dt^2} s^{\mu} = 0$  special relativity

Neighboring particles in free fall have no relative acceleration

Analogy of homogeneous gravitational field



Gravitational field equations

Analogy to Newtonian case

$R^{\mu}_{\nu\rho\sigma}$  contract over two indices

"Ricci tensor"  $R_{\nu\rho} = R^{\mu}_{\nu\rho\mu} = R^0_{\nu\rho 0} + R^1_{\nu\rho 1} + R^2_{\nu\rho 2} + R^3_{\nu\rho 3}$

Analogy to source free Poisson equation  $\nabla^2\phi = 0$

$R_{\nu\rho} = 0$

Riemann curvature scalar  $R = g^{\mu\nu} R_{\mu\nu}$

Analogy to full Poisson equation  $\nabla^2\phi = -4\pi G \rho$

"Einstein tensor"  $G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R = K T_{\mu\nu}$

stress energy tensor of matter

# Schwarzschild spacetime

$$ds^2 = -c^2 \left(1 - \frac{2GM}{c^2 r}\right) dt^2 + \frac{1}{\left(1 - \frac{2GM}{c^2 r}\right)} dr^2 + r^2 d\Omega^2$$

Gives gravitation forces

Gives deviations from Euclidean geometry

line element for a two sphere  
 $d\theta^2 + \sin^2\theta d\phi^2$

Recover gravitational forces in weak field:

$\phi = -\frac{GM}{r}$  consider small  $\phi$ , neglect non-Euclidean geometry

$$ds^2 = -(c^2 + 2\phi) dt^2 + \underbrace{dx^2 + dy^2 + dz^2}_{\text{Euclidean}}$$

Geodesic equation

$$\frac{d^2 x^i}{dt^2} + \Gamma_{\alpha\beta}^i \frac{dx^\alpha}{dt} \frac{dx^\beta}{dt} = 0$$

$i=1,2,3$

only non-zero to lowest order are  $\Gamma_{00}^i = \frac{\partial\phi}{\partial x^i}$

↓ ↓

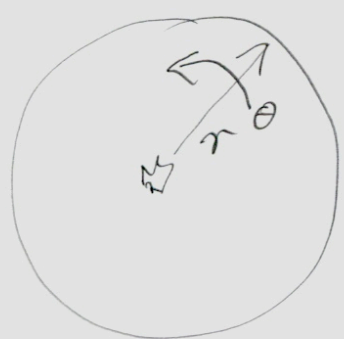
$$\frac{d^2 x^i}{dt^2} + \Gamma_{00}^i \frac{dx^0}{dt} \frac{dx^0}{dt} = 0$$

1 since  $x^0 = t$

$$\frac{d^2 x^i}{dt^2} = - \frac{\partial \phi}{\partial x^i} \quad \dots \quad \text{compare Newtonian Acceleration} = -\nabla \phi$$

**Non-Euclidean geometry**

Take slice at  $t = \text{constant}, \phi = 0$



$$ds^2 = \frac{1}{1 - \frac{2GM}{c^2 r}} dr^2 + r^2 d\theta^2$$

Integrate around circle  $r = \text{constant}$   
 $\theta = 0$  to  $2\pi$

$$\text{circumference} = \int ds = \int_0^{2\pi} r d\theta = 2\pi r = "C(r)"$$

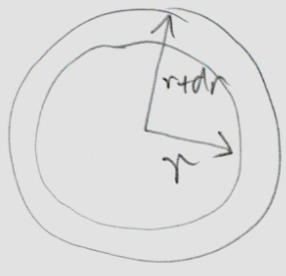
Compare two circles at radii  $r, r+dr$

$$C(r+dr) = 2\pi(r+dr)$$

$$C(r) = 2\pi r$$

Difference

$$dC = 2\pi dr = 2\pi \left(1 - \frac{2GM}{c^2 r}\right) d \text{ true distance}$$



coordinate difference. NOT true length

slightly less than one. Euclidean geometry requires this to be exactly one

# Computing Christoffel symbols

$$\Gamma_{\mu\nu}^{\lambda} = g^{\lambda\sigma} \underbrace{[\mu\nu, \sigma]}$$

$$"g_{\mu\nu, \sigma}" = \frac{\partial g_{\mu\nu}}{\partial x^{\sigma}}$$

$$\frac{1}{2} (g_{\mu\sigma, \nu} + g_{\sigma\nu, \mu} - g_{\mu\nu, \sigma})$$

$$\text{for } ds^2 = -(c^2 + 2\phi) dt^2 + dx^2 + dy^2 + dz^2 \quad \phi = \phi(x, y, z)$$

$\uparrow$   $\uparrow$   $\uparrow$   $\uparrow$   
 $x^0$   $x^1$   $x^2$   $x^3$

$$\text{only non-zero } g_{00, i} = -2\phi_{,i} \quad i=1, 2, 3$$

only non-zero  $[\mu\nu, \sigma]$ :

$$[00, i] = -\frac{1}{2} g_{00, i} \quad [0i, 0] = [i0, 0] = \frac{1}{2} g_{00, i}$$

$$= \phi_{,i} \quad = -\phi_{,i}$$

compute  $g^{\mu\nu}$

$$g_{\mu\nu} \approx \begin{bmatrix} -\frac{1}{c^2} & 0 \\ 0 & 1, 1, 1 \end{bmatrix}$$

$$\text{since } g^{\mu\nu} g_{\nu\sigma} = \delta_{\sigma}^{\mu}$$

$$\begin{bmatrix} -\frac{1}{c^2(1+\frac{2\phi}{c^2})} & 0 \\ 0 & 1, 1, 1 \end{bmatrix} \begin{bmatrix} -c^2(1+\frac{2\phi}{c^2}) \\ & & & \end{bmatrix} = \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

$$-\frac{1}{c^2(1+\frac{2\phi}{c^2})} \approx -\frac{1}{c^2} \left(1 - \frac{2\phi}{c^2}\right) \approx -\frac{1}{c^2}$$

7  
Only non-zero  $\Gamma_{\mu\nu}^\lambda$

$$\Gamma_{00}^i = g^{\bar{i}\bar{i}} \{00, \bar{i}\} = \phi_{,i} \quad \bar{i}=1,2,3$$

$$\Gamma_{i0}^0 = \Gamma_{0i}^0 = g^{00} \phi_{,i} = \frac{1}{c^2} \phi_{,i} \approx 0 \text{ to lowest order}$$

At lowest order, only non-zero  $\Gamma_{\mu\nu}^\lambda$

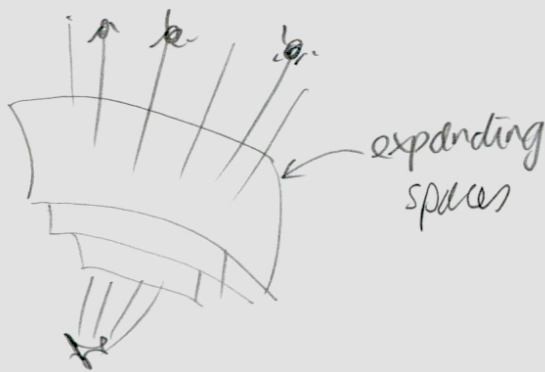
$$\Gamma_{00}^i = \phi_{,i} = \frac{\partial \phi}{\partial x^i}$$

# Friedmann-Lemaître-Robertson-Walker spacetimes

$$ds^2 = -c^2 dt^2 + a^2(t) \left[ \frac{dr^2}{1-kr^2} + r^2 d\Omega^2 \right]$$

Dynamics lives  
in time dependence  
of scale factor

Geometry of:  
 $k=1$  3-sphere  
 $k=0$  Euclid  
 $k=-1$  3-hyperbolic



Solve Einstein equations for matter density  $\rho$   
and pressure  $p$

$$\dot{a}(t) = \frac{da(t)}{dt} \quad \ddot{a}(t) = \frac{d^2a(t)}{dt^2}$$

with  $c=1$

$$\left( \frac{\dot{a}}{a} \right)^2 = \frac{8\pi G}{3} \rho - \frac{k}{a^2}$$

$$\frac{\ddot{a}}{a} = -\frac{4\pi G}{3} (\rho + 3p)$$