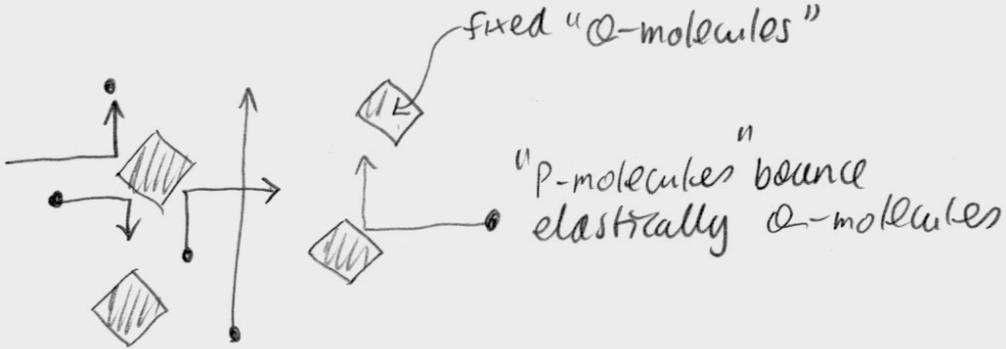
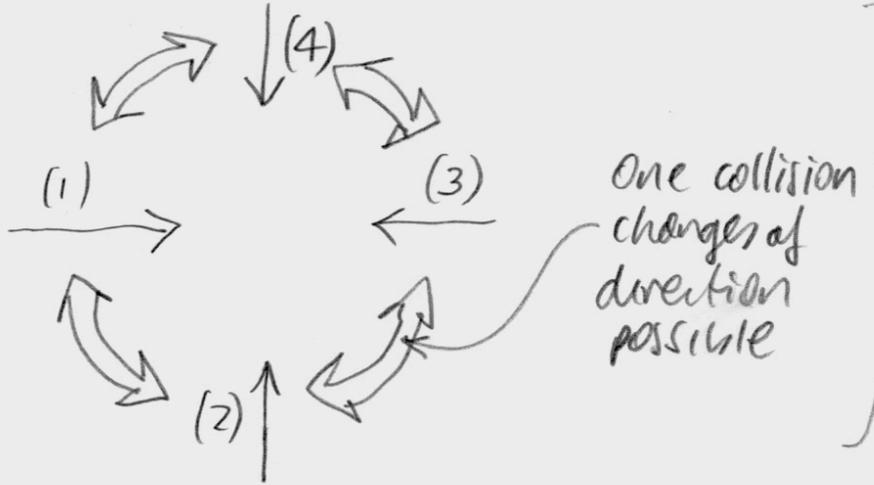


Ehrenfest's "Wind Tree" model shows how a time reversible dynamics can lead to a unidirectional approach to equilibrium

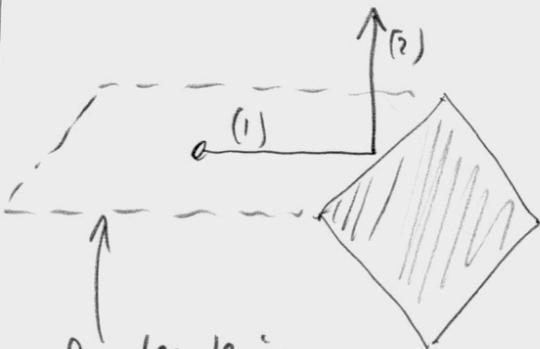
System is a plane



P-molecules initially & always confined to four directions of motion



Collision dynamics



P molecules in this area will collide & move from (1) to (2)

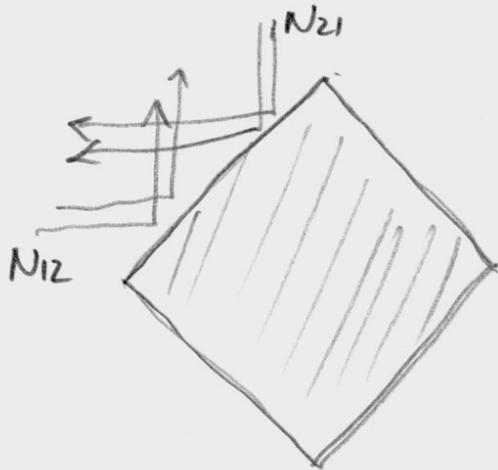
$$\text{Area} = \underbrace{k}_{\text{constant}} \underbrace{dt}_{\text{time interval}}$$

Stosszahlansatz

$$N_{12} \Delta t = \underbrace{f_1}_{\text{Number of transitions}} \cdot \underbrace{k}_{\text{Number of P molecules moving with velocity (1)}} \cdot \underbrace{\Delta t}_{\text{area}}$$

Approach to Equilibrium

Typical
interchange
mechanism



Without
Stoßzahlansatz
this
equilibrating
mechanism is
not available

Net rate
transfer
(1) \rightarrow (2) by
this mechanism

$$= N_{12} - N_{21} = k(f_1 - f_2)$$

- \therefore Transfer rate (1) \rightarrow (2) is positive when $f_1 > f_2$
- is negative when $f_1 < f_2$

Hence mechanism drives numbers towards
limit $f_1 = f_2$

Same for all interchange mechanisms

\therefore collisions
drive system
towards $f_1 = f_2 = f_3 = f_4$

Dynamics

$$\frac{df_1}{dt} = \underbrace{(-N_{12} - N_{14})}_{\text{Rate reduction (1) motions}} + \underbrace{(N_{21} + N_{41})}_{\text{Rate creation (1) motions}}$$

$$= k(-2f_1 + f_2 + f_4)$$

similarly

$$\frac{df_2}{dt} = k(-2f_2 + f_1 + f_3)$$

$$\frac{df_3}{dt} = k(-2f_3 + f_4 + f_2)$$

$$\frac{df_4}{dt} = k(-2f_4 + f_1 + f_3)$$

↓ sum

$$\frac{d}{dt} (f_1 + f_2 + f_3 + f_4) = k \left(-2(f_1 + f_2 + f_3 + f_4) + (f_2 + f_4) + (f_1 + f_3) + (f_2 + f_4) + (f_1 + f_3) \right) = 0$$

As expected $f_1 + f_2 + f_3 + f_4 = N$
 ↑ total number of P-molecules

Compare f_1, f_3

$$\frac{1}{k} \frac{d}{dt} (f_1 - f_3) = -2f_1 + f_2 + f_4 + 2f_3 - f_2 - f_4 = -2(f_1 - f_3)$$

$$f_1(t) - f_3(t) = [f_1(0) - f_3(0)] \exp(-2kt)$$

$f_1(t) \rightarrow f_3(t)$ as $t \rightarrow \infty$

Similarly f_2, f_4

$$f_2(t) - f_4(t) = [f_2(0) - f_4(0)] \exp[-2kt]$$

$f_2(t) \rightarrow f_4(t)$ as $t \rightarrow \infty$

Still need: show $f_1(t) \rightarrow f_2(t)$ when $t \rightarrow \infty$
 otherwise we cannot preclude
 oscillations in $f_1 \approx f_3$ counterbalanced
 by oscillations in $f_2 \approx f_4$

Compare $(f_1 + f_3)$ with $(f_2 + f_4)$

$$\frac{1}{k} \frac{d}{dt} (f_1 + f_3) = -2(f_1 + f_3) + 2(f_2 + f_4)$$

$$-\frac{1}{k} \frac{d}{dt} (f_2 + f_4) = -[-2(f_2 + f_4) + 2(f_1 + f_3)]$$

$$= -4[(f_1 + f_3) - (f_2 + f_4)]$$

Hence solving

$$[(f_1 + f_3) - (f_2 + f_4)] = (f_1(0) + f_3(0)) - (f_2(0) + f_4(0))$$

$$\exp(-4kt)$$

$$i.e. f_1(t) + f_3(t) \longrightarrow f_2(t) + f_4(t) \quad \text{as } t \rightarrow \infty$$

Combining

$$\text{All } f_1(t), f_2(t), f_3(t), f_4(t) \longrightarrow \text{same value} = \frac{N}{4}$$

$$\text{as } t \rightarrow \infty$$