## Solutions

- 1. Consider the following ordinary differential equation (ODE)  $y' + \frac{2}{r}y = \frac{\sin x}{r^2}$ 
  - (a) Find the explicit general solution to this ODE.

Solution: It is a linear equation. The integrating factor is  $u = e^{\int \frac{2}{x} dx} = x^2$   $x^2y' + 2xy = \sin x$ ,  $(x^2y)' = \sin x$ ,  $x^2y = \int \sin x \, dx = -\cos x + c$ . Therefore,  $y = -\frac{\cos x}{r^2} + \frac{c}{r^2} = \frac{c - \cos x}{r^2}$ .

(b) Find the particular solution that satisfies  $y(\pi) = 0$ .

Solution:  $c - \cos \pi = 0$ ,  $c = \cos \pi = -1$ .

Therefore,  $y = -\frac{1 + \cos x}{x^2}$ .

(c) Find the interval of existence on which the particular solution with  $y(\pi) = 0$  is valid.

Solution:  $x \neq 0$  and  $x = \pi$  is in the interval.

Therefore the interval of existence is  $(0, \infty)$ .

- 2. The ODE for the displacement of a spring, which is undamped and forced, takes the form  $y'' + y = 2\sin t.$ 
  - (a) Find the transient state, i.e. the solution to the associated homogeneous equation.

Solution: Homogeneous equation is y'' + y = 0.

Char. eq. is  $\lambda^2 + 1 = 0$ . It has complex (pure imaginary) roots  $\lambda = i$  and  $\bar{\lambda} = -i$ .

FSS:  $y_1(t) = \cos t, \ y_2(t) = \sin t.$ 

The transient state is  $y(t) = c_1 \cos t + c_2 \sin t$ .

(b) Find the steady-state, i.e. a particular solution, to the forced equation.

Solution: Because the forcing term coincide with one of the fundamental solutions the trial particular solution is

$$y_p(t) = t(a\cos t + b\sin t) = tv$$
, where  $v = a\cos t + b\sin t$ .

Note that  $v' = -a \sin t + b \cos t$  and v'' = -v.

$$y'_p = v + tv', \quad y''_p(t) = v' + v' + tv'' = 2v' - tv.$$
 Then

$$y_p'' + y_p = 2v' - tv + tv = 2v' = -2a\sin t + 2b\cos t = 2\sin t \implies a = -1, b = 0.$$

$$y_p(t) = -t \cos t$$
.

(c) Find the general solution.

Solution: The general solution is  $y(t) = c_1 \cos t + c_2 \sin t - t \cos t$ .

3. Find the solution to the previous ODE  $y'' + y = 2 \sin t$  that satisfy the initial conditions y(0) = 0, y'(0) = -1. Use Laplace transform.

$$\left[ \text{ Hint: } \frac{2}{(s^2+1)^2} - \frac{1}{s^2+1} = \frac{1-s^2}{(s^2+1)^2} = \frac{d}{ds} \left( \frac{s}{s^2+1} \right) \right]$$

Solution: 
$$L[y'' + y] = L[2\sin t], \quad (s^2 + 1)Y(s) + 1 = \frac{2}{s^2 + 1}, \quad Y(s) = \frac{2}{(s^2 + 1)^2} - \frac{1}{s^2 + 1}.$$

$$Y(s) = \frac{d}{ds} \left( \frac{s}{s^2 + 1} \right)$$

Therefore,  $y(t) = -t \cos t$  (by using the derivative of Laplace transform formula).

4. For the system of nonlinear differential equations

$$x' = x(3 - x - y)$$

$$y' = x - 2y$$

(a) Find x-nullcline and y-nullcline. Draw a plot.

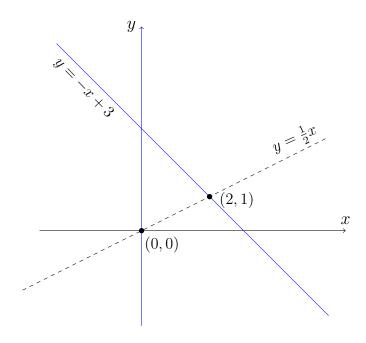
Solution: x-nullcline:  $x(3-x-y)=0 \Leftrightarrow x=0 \text{ or } y=-x+3.$ 

Therefore, x-nullcline is a union of two lines x = 0 and y = -x + 3

(solid blue lines on the plot below).

y-nullcline: 
$$x - 2y = 0 \iff y = \frac{1}{2}x$$
.

Therefore, y-nullcline is the line  $y = \frac{1}{2}x$  (dashed line).



(b) Find equilibrium points. Clearly mark them on the plot.

Solution: There are two equilibrium points (0,0) and (2,1).

(c) Find Jacobian matrix at every equilibrium point. Determine types of all equilibrium points of the given nonlinear system. If the type cannot be determined, explain why.

Solution: 
$$J = \begin{bmatrix} 3 - 2x - y & -x \\ 1 & -2 \end{bmatrix}$$

At 
$$(0,0)$$
:  $J(0,0) = \begin{bmatrix} 3 & 0 \\ 1 & -2 \end{bmatrix}$ 

 $D = \det J = -6 < 0$ ,  $\Rightarrow$  the linearization of the given system has a saddle at (0,0). This type is generic. Therefore the nonlinear system has a saddle at (0,0).

At 
$$(2,1)$$
:  $J(2,1) = \begin{bmatrix} -2 & -2 \\ 1 & -2 \end{bmatrix}$ 

 $D = \det J = 4 + 2 = 6 > 0$ , T = -4 < 0,  $T^2 - 4D = 16 - 24 = -8 < 0 \Rightarrow$  the linearization of the given system has a spiral sink at (2,1). This type is generic. Therefore the nonlinear system has a spiral sink at (2,1).

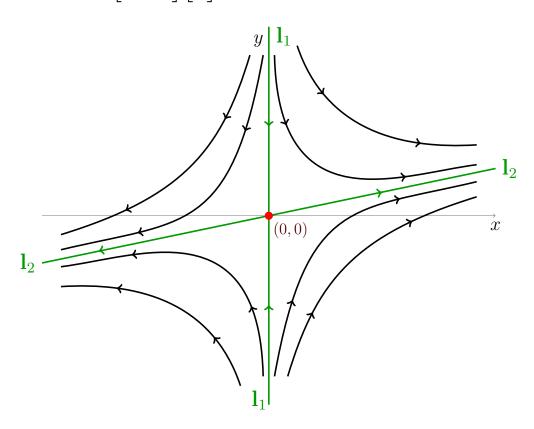
(d) For the most left equilibrium point find eigenvalues of the corresponding linear system and its eigenvectors. Draw the local phase portrait near the equilibrium point.

Solution: The most left equilibrium point is (0,0).

$$T = 1 > 0, \ T^2 - 4D = 1 + 24 = 25 \ \Rightarrow \ \lambda_1 = -2, \ \lambda_2 = 3.$$

$$(J - \lambda_1 I)\bar{\mathsf{v}}_1 = \begin{bmatrix} 5 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \bar{\mathsf{0}} \quad \Rightarrow \quad v_1 = 0. \text{ Take } v_2 = 1 \quad \Rightarrow \quad \bar{\mathsf{v}}_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$

$$(J - \lambda_2 I)\bar{\mathbf{v}}_2 = \begin{bmatrix} 0 & 0 \\ 1 & -5 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \bar{\mathbf{0}} \quad \Rightarrow \quad v_1 - 5v_2 = 0 \quad \Leftrightarrow \quad v_1 = 5v_2 \quad \Rightarrow \quad \bar{\mathbf{v}}_2 = \begin{bmatrix} 5 \\ 1 \end{bmatrix}.$$



5. Expand the function  $f(x) = |x|, -1 \le x \le 1$  in a Fourier series.

Solution: f(x) is even. Therefore all  $b_n = 0$  and

$$a_0 = 2 \int_0^1 x \, dx = 1$$
,  $a_n = 2 \int_0^1 x \cos(n\pi x) \, dx = \frac{2}{\pi^2} \cdot \frac{(-1)^n - 1}{n^2}$ .

Then 
$$|x| = \frac{1}{2} + \frac{2}{\pi^2} \sum_{n=1}^{\infty} \frac{(-1)^n - 1}{n^2} \cos(n\pi x).$$

Alternative answer is  $|x| = \frac{1}{2} - \frac{4}{\pi^2} \sum_{k=0}^{\infty} \frac{1}{(2k+1)^2} \cos((2k+1)\pi x).$ 

6. Given the equation

$$u_t(x,t) = u_{xx}(x,t) + \frac{1}{t} \cdot u(x,t), \qquad 0 < x < \pi$$

with boundary conditions

$$u(0,t) = 0, \ u(\pi,t) = 0$$

(a) perform separation of variables, find the ODEs for T(t) and X(x).

Solution: 
$$u = XT$$
,  $u_t = XT'$ ,  $u_{xx} = X''T$ 

$$XT'=X''T+\frac{1}{t}\cdot XT,\quad X\left(T'-\frac{1}{t}\cdot T\right)=X''T,\quad \frac{T'}{T}-\frac{1}{t}=\frac{X''}{X}=-\lambda=-\omega^2.$$

Therefore, 
$$\frac{T'}{T} = \frac{1}{t} - \omega^2$$
,  $X'' + \omega^2 X = 0$ .

(b) Find boundary conditions for X(x).

Solution: 
$$X(0) = 0, X(\pi) = 0.$$

(c) From the ODE for X(x), find the eigenvalues  $\lambda_n$  and the eigenfunctions  $X_n(x)$ .

Solution: 
$$X(x) = a\cos\omega x + b\cos\omega x$$
.

$$X(0) = a = 0, \ X(x) = b\cos\omega x, \ X(\pi) = b\cos\omega \pi = 0, \ \omega\pi = n\pi, \ \omega_n = n.$$

The eigenvalues are  $\lambda_n = n^2$ .

The eigenfunctions are  $X_n(x) = \cos nx$  (or  $b_n \cos nx$ ).

(d) Solve the ODE for T(t) to find  $T_n(t)$  that corresponds to  $\lambda_n$ .

Solution: 
$$\frac{T'}{T} = \frac{1}{t} - n^2$$
.

It is a separable equation.  $\ln T = \ln t - n^2 t + c$ ,  $T_n(t) = Ate^{-n^2 t}$ 

bonus problem Find Fourier Series expansion of the Dirac's delta function  $\delta(x)$ . You can assume that  $L=\pi$ .

Solution: 
$$\int_{-a}^{a} \delta(x) dx = 1, \int_{-a}^{a} \delta(x) f(x) dx = f(0) \text{ for any } a > 0$$

by the property of the delta function.

Therefore, 
$$b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} \delta(x) \sin(nx) dx = \frac{1}{\pi} \sin(0) = 0.$$

$$a_0 = \frac{1}{\pi} \int_{-\pi}^{\pi} \delta(x) \, dx = \frac{1}{\pi} \cdot 1 = \frac{1}{\pi}.$$

$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} \delta(x) \cos(nx) dx = \frac{1}{\pi} \cos(0) = \frac{1}{\pi}.$$

Then 
$$\delta(x) = \frac{1}{2\pi} + \frac{1}{\pi} \sum_{n=1}^{\infty} \cos(nx)$$
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