

## Coupled differential equations

Example:

4/1/2018

$$\frac{dy_1}{dx} = a_{11}y_1 + a_{12}y_2 + b_1(x)$$

$$\frac{dy_2}{dx} = a_{21}y_1 + a_{22}y_2 + b_2(x)$$

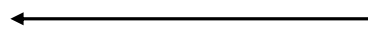
Consider the case with  $b_1 = b_2 = 0$

$$\frac{d}{dt} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$\frac{d\mathbf{y}}{dt} = \mathbf{A}\mathbf{y} \Rightarrow \mathbf{y} = e^{\mathbf{A}t}\mathbf{y}_0$$

One way to address this sort of problem, is to find the eigenvalues of the matrix and transform to the diagonal representation

Let  $\mathbf{y} = \mathbf{P}\mathbf{z}$



change of basis set

$$\frac{d\mathbf{y}}{dx} = \mathbf{P} \frac{d\mathbf{z}}{dx} = \mathbf{A}\mathbf{P}\mathbf{z}$$

with the proper choice of  $\mathbf{P}$ , we can diagonalize  $\mathbf{A}$

$$\mathbf{P}^{-1}\mathbf{A}\mathbf{P} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

$$\mathbf{P}^{-1} \frac{d\mathbf{y}}{dx} = \frac{d\mathbf{z}}{dx} = \mathbf{P}^{-1}\mathbf{A}\mathbf{P}\mathbf{z} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$$

$$\frac{dz_1}{dx} = \lambda_1 z_1 \rightarrow z_1 = c_1 e^{\lambda_1 x}$$

$$\frac{dz_2}{dx} = \lambda_2 z_2 \rightarrow z_2 = c_2 e^{\lambda_2 x}$$

Note:  $\mathbf{A}$  might not be Hermitian (or even symmetric). In such a case  $\mathbf{P}^{-1}$  can be determined using cofactors and the determinant  
(See [updated notes on Matrices](#))

to find  $\mathbf{y}$  multiply  $\mathbf{z}$  by  $\mathbf{P}$

$$\mathbf{y} = \mathbf{P}\mathbf{z}$$

Example  $\frac{dy_1}{dx} = y_1 + 2y_2$   
 $\frac{dy_2}{dx} = 2y_1 + y_2$

$$A = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \Rightarrow \begin{vmatrix} 1-\lambda & 2 \\ 2 & 1-\lambda \end{vmatrix} = (1-\lambda)^2 - 4 = 0$$

$$1-\lambda = \pm 2 \Rightarrow \lambda = -1, +3$$

$$(1+1)a_1 + 2a_2 = 0 \Rightarrow a_1 = -a_2 \Rightarrow P = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}$$

$$(1-3)a_1 + 2a_2 = 0 \Rightarrow a_1 = a_2$$

$$z_1 = c_1 e^{-x}, \quad z_2 = c_2 e^{3x}$$

$$\mathbf{y} = P\mathbf{z}$$

$$\mathbf{y} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} c_1 e^{-x} \\ c_2 e^{3x} \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} c_1 e^{-x} + c_2 e^{3x} \\ -c_1 e^{-x} + c_2 e^{3x} \end{pmatrix}$$

$$y_1 = \frac{1}{\sqrt{2}} (c_1 e^{-x} + c_2 e^{3x})$$

$$\frac{dy_1}{dt} = \frac{1}{\sqrt{2}} (-c_1 e^{-x} + 3c_2 e^{3x})$$

$$y_1 + 2y_2 = c_1 e^{-x} + c_2 e^{3x} + 2(-c_1 e^{-x} + c_2 e^{3x}) = -c_1 e^{-x} + 3c_2 e^{3x}$$

$$\begin{aligned} & \begin{pmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \\ & = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} -1 & 3 \\ 1 & 3 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -2 & 0 \\ 0 & 6 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 3 \end{pmatrix} \end{aligned}$$

Consistency check

Higher order differential equations can be converted to systems of first-order equations

Consider  $m \frac{d^2x}{dt^2} + kx = 0$

$$\frac{d^2x}{dt^2} + \frac{kx}{m} = 0$$

Let  $\frac{dx}{dt} = v$

Then

$$\frac{dv}{dt} + \frac{kx}{m} = 0$$

$$\frac{dx}{dt} - v = 0$$

$$\frac{d}{dt} \begin{pmatrix} v \\ x \end{pmatrix} = \begin{pmatrix} 0 & k/m \\ -1 & 0 \end{pmatrix} \begin{pmatrix} v \\ x \end{pmatrix}$$

Thus, we have converted 2<sup>nd</sup>-order differential equation to two coupled first-order equations

Initial conditions

$$x(0) = x_0 \quad v(0) = v_0$$

Can solve using matrix techniques

Can also solve numerically using Euler or Runge Kutta methods

Consider Euler

$$x(1) = x(0) - v(0)\Delta t$$

$$v(1) = v(0) - \frac{k}{m}x(0)\Delta t$$

↓

$$x(2) = x(1) - v(1)\Delta t$$

$$v(2) = v(1) - \frac{k}{m}x(1)\Delta t$$

⋮

Note: could also use  $x_1$  at this point since the first equation gives a new value of  $x$ .

See posted handout as to how to solve numerically with Mathematica

## Power series solutions to differential equations

E.g.  $\frac{dy}{dt} = ky$  | suppose we didn't know how to solve this

Write  $y = a_0 + a_1t + a_2t^2 + \dots = \sum_{n=0}^{\infty} a_n t^n$

$$\frac{dy}{dt} = a_1 + 2a_2t + 3a_3t^2 + \dots = k[a_0 + a_1t + a_2t^2 + \dots] \Rightarrow$$
$$(a_1 - ka_0) + (2a_2 - ka_1)t + (3a_3 - ka_2)t^2 + \dots = 0$$

For this to be satisfied in the general case, each term in parentheses must be 0.

$$\Rightarrow a_1 = ka_0$$

$$a_2 = \frac{1}{2}ka_1 = \frac{1}{2}k^2a_0$$

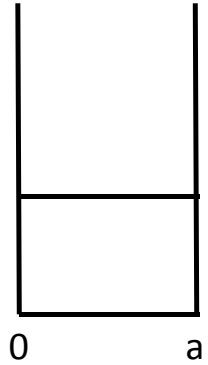
$$a_3 = \frac{1}{3}ka_2 = \frac{1}{3 \cdot 2}k^2a_1 = \frac{1}{3 \cdot 2}k^3a_0$$

The eq. expressing the high order coefficients in terms of lower order coefficients is called a recursion relation

$$y = a_0 \left[ 1 + kt + \frac{1}{2}(kt)^2 + \frac{1}{6}(kt)^3 \dots \right]$$

$$y = a_0 e^{kt}$$

$$t = 0 \Rightarrow a_0 = y_0 \Rightarrow y = y_0 e^{kt}$$



Now let's treat the quantum mechanical particle-in-the-box problem

$$\frac{-\hbar^2}{2m} \frac{d^2}{dx^2} \Psi = E\Psi, \quad 0 \leq x \leq a$$

Inside the box

$$\frac{d^2}{dx^2} \psi = -\alpha\psi, \quad \alpha = \frac{2mE}{\hbar^2}$$

$$\frac{d^2\psi}{dx^2} + \alpha\psi = 0$$

$$\left[ 2a_2 + 3 \cdot 2a_3x + 4 \cdot 3x^2 + \dots \right] + \alpha \left[ a_0 + a_1x + a_2x^2 + \dots \right]$$

$$2a_2 + \alpha a_0 = 0 \rightarrow a_2 = -\frac{\alpha}{2} a_0$$

$$6a_3 + \alpha a_1 = 0 \rightarrow a_3 = -\frac{\alpha}{6} a_1$$

$$12a_4 + \alpha a_2 = 0 \rightarrow a_4 = -\frac{\alpha}{4 \cdot 3} a_2 = \frac{\alpha^2}{4 \cdot 3 \cdot 2} a_0$$

$$20a_5 + \alpha a_3 = 0 \rightarrow a_5 = -\frac{\alpha}{5 \cdot 4} a_3 = \frac{\alpha^2}{5 \cdot 4 \cdot 3 \cdot 2} a_1$$

recursion relations

$$\psi = a_0 \left[ 1 - \frac{\alpha}{2} x^2 + \frac{\alpha^2}{4 \cdot 3 \cdot 2} x^4 + \dots \right] + a_1 \left[ x - \frac{\alpha}{3 \cdot 2} x^3 + \frac{\alpha^2}{5 \cdot 4 \cdot 3 \cdot 2} x^5 - \dots \right]$$

We also know  $\psi(0) = 0 \Rightarrow a_0 = 0$

Note  $\sin(kx) = kx - \frac{(kx)^3}{3!} + \frac{(kx)^5}{5!} - \dots$

$$\frac{1}{k} \sin(kx) = x - \frac{(k^2 x^3)}{3!} + \frac{k^4 x^5}{5!} - \dots$$

$$\psi = \frac{1}{\sqrt{\alpha}} \left[ \sqrt{\alpha} x - \frac{\alpha^{3/2} x^3}{3!} + \frac{\alpha^{5/2} x^5}{5!} - \dots \right] = \frac{1}{k} \sin(kx) \quad \left| \text{let } k^2 = \alpha \right.$$

Apply boundary condition at  $x = a$

$$\sqrt{\alpha} a = n\pi \Rightarrow \sqrt{\alpha} = \frac{n\pi}{a}$$

$$\sin(kx) = \sin\left(\frac{n\pi x}{a}\right)$$

$$\alpha = \frac{2mE}{\hbar^2} = \frac{n^2 \pi^2}{a^2}$$

but

$$E_n = \frac{n^2 \pi^2 \hbar^2}{2ma^2} = \frac{n^2 \hbar^2}{8ma^2}, \quad n = 1, 2, 3, \dots$$

$$n = 1: E_1, \psi_1$$

$$n = 2: E_2, \psi_2$$

etc.



Now consider the quantum harmonic oscillator

$$-\frac{\hbar^2}{2m} \frac{d^2\psi}{dx^2} + \frac{1}{2} kx^2\psi = E\psi$$

$$-\frac{d^2\psi}{dx^2} + \frac{mk}{\hbar^2} x^2\psi = \frac{2mE}{\hbar^2} \psi$$

$$-\frac{d^2\psi}{dx^2} + \alpha x^2 = \varepsilon \psi$$

try  $\psi = e^{-ax^2}$

$$\psi' = -2axe^{-ax^2}$$

$$\psi'' = (-2a + 4a^2x^2)e^{-ax^2} \Rightarrow$$

$$-(-2a + 4a^2x^2) + \alpha x^2 = \varepsilon$$

$$\varepsilon = 2a, \quad \alpha = 4a^2$$

$$+\frac{2mE}{\hbar^2} = 2a, \quad E = \frac{\hbar^2 a}{m}$$

$$a = \frac{\sqrt{\alpha}}{2} = \frac{\sqrt{mk}}{2\hbar}$$

$$E = \frac{\hbar^2}{m} \frac{\sqrt{mk}}{2\hbar} = \sqrt{\frac{k}{m}} \frac{\hbar}{2} = \frac{1}{2} \hbar \omega = \frac{1}{2} h\nu$$

We will see later how we can solve for the excited state.

What would be reasonable guess for the wave function of the first excited state?

For a general solution, we could try  $\psi = e^{-ax^2} [a_0 + a_1x + \dots]$

## Non-linear differential equations

### Logistic equation

$$\frac{dA}{dt} = \varepsilon A - \sigma A^2, \quad A = \text{population}$$

$\varepsilon A$  → population growth

$-\sigma A^2$  → intraspecies competition for resources

In the absence of the  $\sigma A^2$  term

$$\frac{dA}{dt} = \varepsilon A \Rightarrow A = A_0 e^{\varepsilon t}$$

Critical points (equilibrium points)

$$\frac{dA}{dt} = \varepsilon A - \sigma A^2,$$

$$\varepsilon A - \sigma A^2 = 0$$

$$\Rightarrow A = 0,$$

$$\text{or } A = \varepsilon / \sigma$$

if  $A \neq 0$  or  $\varepsilon / \sigma$

$$\frac{dA}{\varepsilon A - \sigma A^2} = dt$$

$$\left( \frac{1}{A} + \frac{-1}{A - \frac{\varepsilon}{\sigma}} \right) dA = \varepsilon dt$$

$$\ln(A) - \ln\left(A - \frac{\varepsilon}{\sigma}\right) = \varepsilon t$$

$$\ln\left(\frac{-\varepsilon / \sigma + A}{A}\right) = -\varepsilon t$$

$$\begin{aligned} \left( \frac{1}{A} + \frac{-1}{A - \frac{\varepsilon}{\sigma}} \right) &= \frac{(A - \frac{\varepsilon}{\sigma}) - A}{A\left(A - \frac{\varepsilon}{\sigma}\right)} \\ &= \frac{-\frac{\varepsilon}{\sigma}}{A^2 - \frac{\varepsilon}{\sigma}A} = \frac{\varepsilon}{-A^2\sigma + \varepsilon A} \end{aligned}$$

$$\frac{-\varepsilon / \sigma + A}{A} = ce^{-\varepsilon t}$$

$$-\varepsilon / \sigma + A = Ace^{-\varepsilon t}$$

$$A(ce^{-\varepsilon t} - 1) = -\varepsilon / \sigma$$

$$A = \frac{\varepsilon / \sigma}{1 - ce^{-\varepsilon t}}$$

if  $A(0) = A_0$

$$A_0 = \frac{\varepsilon / \sigma}{1 - c} \rightarrow$$

$$(1 - c)A_0 = \varepsilon / \sigma$$

$$cA_0 = A_0 - \varepsilon / \sigma$$

$$c = \frac{A_0 - \varepsilon / \sigma}{A_0}$$

$$A_0 = 0 \Rightarrow A = 0$$

$$A_0 = \varepsilon / \sigma \Rightarrow A = \varepsilon / \sigma \text{ carrying capacity}$$

With either of these initial conditions, the population does not change with time

$$A = \frac{\epsilon}{\sigma + \left[ \frac{\epsilon - \sigma A_0}{A_0} \right] e^{-\epsilon t}}$$

As  $t \rightarrow \infty$   $A \rightarrow \epsilon / \sigma =$  carrying capacity (if  $A_0 \neq 0$ )

Limiting behavior can often be established without solving the differential equation

Consider plot of  $dA/dt$  vs.  $A$ ,  $\epsilon > 0$ ,  $\sigma > 0$

if  $dA/dt +$ ,  $A$  increases toward  $\epsilon / \sigma$

if  $dA/dt -$ ,  $A$  decreases toward  $\epsilon / \sigma$

$A = 0$  is an **unstable critical point**, since if  $A_0$  is only infinitesimally  $> 0$ , the system evolves to  $\epsilon / \sigma$

$A = \epsilon / \sigma$  is an **asymptotically stable critical point**

Now consider  $\epsilon < 0$ ,  $\sigma < 0$

any start with  $0 < A_0 < \epsilon / \sigma$  evolves to 0

any start with  $A_0 > \epsilon / \sigma$  grows without bound

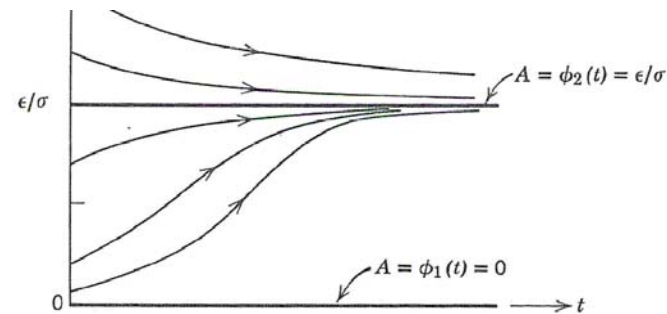


FIGURE 9.1  $dA/dt = \epsilon A - \sigma A^2$ ,  $\epsilon > 0$ ,  $\sigma > 0$ .

From Boyce and DiPrima

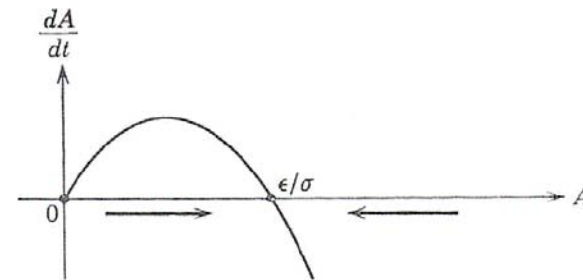


FIGURE 9.2  $dA/dt = \epsilon A - \sigma A^2$ ,  $\epsilon > 0$ ,  $\sigma > 0$ .

From Boyce and DiPrima

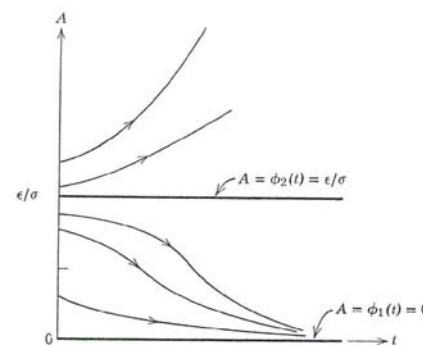


FIGURE 9.5  $dA/dt = \epsilon A - \sigma A^2$ ,  $\epsilon < 0$ ,  $\sigma < 0$ .

From Boyce and DiPrima

## Coupled Non-linear Differential Equations

$$\frac{dx}{dt} = F(x, y)$$

$$\frac{dy}{dt} = G(x, y)$$

### Example

$$\frac{dx}{dt} = \varepsilon_1 x - \sigma_1 x^2 - \alpha_1 xy = x(\varepsilon_1 - \sigma_1 x - \alpha_1 y)$$

$$\frac{dy}{dt} = \varepsilon_2 y - \sigma_2 y^2 - \alpha_2 xy = y(\varepsilon_2 - \sigma_2 y - \alpha_2 x)$$

$$x = 0, \quad 2^{\text{nd}} \text{ equation} \quad \varepsilon_2 - \sigma_2 y = 0$$

$$y = 0, \quad 1^{\text{st}} \text{ equation} \quad \varepsilon_1 - \sigma_1 x = 0$$

critical points  $(x, y) = (0, 0), (0, \varepsilon_2 / \sigma_2), (\varepsilon_1 / \sigma_1, 0)$

also constant solution if  $\varepsilon_1 - \sigma_1 x - \alpha_1 y$  and  $\varepsilon_2 - \sigma_2 y - \alpha_2 x$  intersect.

With increasing time:

$x$  increases (decreases) if  $\varepsilon_1 - \sigma_1 x - \alpha_1 y > (<) 0$

$y$  increases (decreases) if  $\varepsilon_2 - \sigma_2 y - \alpha_2 x > (<) 0$

## Example

$$\frac{dx}{dt} = x(1-x-y)$$

$$\frac{dy}{dt} = y\left(\frac{1}{2} - \frac{1}{4}y - \frac{3}{4}x\right)$$

critical points  $(0,0)$ ,  $(0,2)$ ,  $(1,0)$ ,  $\left(\frac{1}{2}, \frac{1}{2}\right)$

In many cases, one can learn about the behavior of the solutions in the vicinity of the various critical points by **linearizing** about each critical point

E.g.,  $(0,0)$

$$\frac{dx}{dt} = x, \quad \frac{dy}{dt} = \frac{1}{2}y$$

$$x = e^t$$

$$y = e^{0.5t}$$

This is an unstable critical point

$$\frac{dx}{dt} = x(1-x-y)$$

$$\frac{dy}{dt} = y\left(\frac{1}{2} - \frac{1}{4}y - \frac{3}{4}x\right)$$

Now consider  $(x, y) = (1, 0)$

Let  $x = u + 1$ ,  $y = v$

$$\frac{du}{dt} = -u - v - u^2 - uv$$

$$\frac{dv}{dt} = -\frac{1}{4}v - \frac{1}{4}v^2 - \frac{3}{4}uv$$

Linearize

$$\frac{du}{dt} = -u - v, \quad \frac{dv}{dt} = -\frac{1}{4}v$$

$$u = -\frac{4}{3}Ae^{-t/4} + Be^{-t}, \quad v = Ae^{-t/4}$$

This is an **asymptotically stable point**

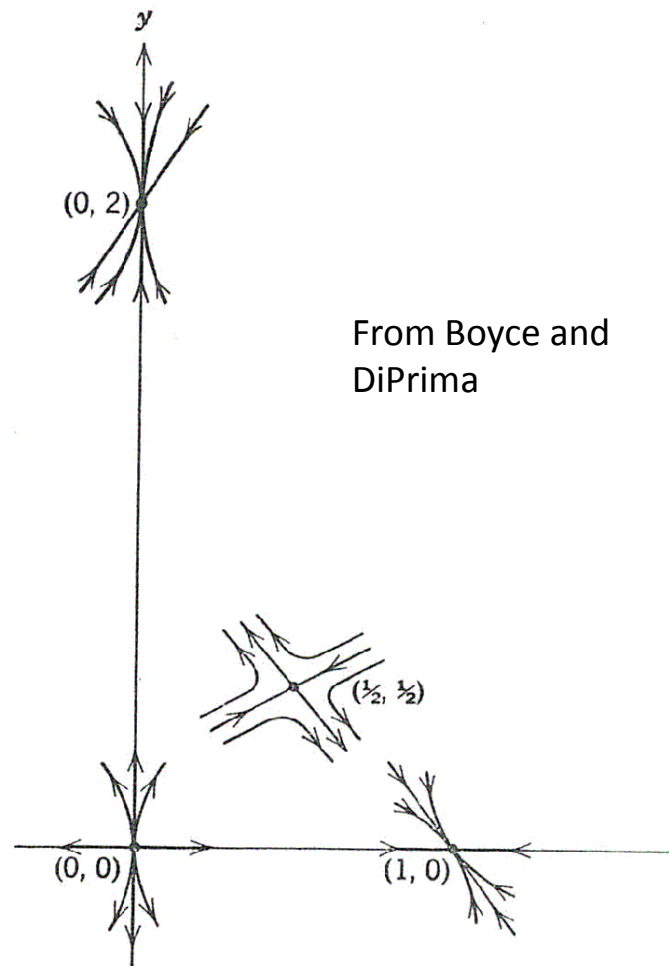


FIGURE 9.27a



Specialize to predator-prey problem

$$\frac{dR}{dt} = aR - \alpha RF \quad \left| \quad \text{Rabbit} \right.$$

$$\frac{dF}{dt} = -cF + \gamma RF \quad \left| \quad \text{Fox} \right.$$

assume all constants  
are positive

Find the critical points

$$R(a - \alpha F) = 0$$

$$F(-c + \gamma R) = 0$$

$$\text{critical points } (R, F) = (0, 0), \left( \frac{c}{\gamma}, \frac{a}{\alpha} \right)$$

For the critical point  $(R, F) = \left(\frac{c}{\gamma}, \frac{a}{\alpha}\right)$

$$R = \frac{c}{\gamma} + r \quad F = \frac{a}{\alpha} + f$$

$$\frac{dR}{dt} = aR - \alpha RF, \quad \frac{dF}{dt} = -cF + \gamma RF$$

$$\frac{dr}{dt} = a\left(\frac{c}{\gamma} + r\right) - \alpha\left(\frac{c}{\gamma} + r\right)\left(\frac{a}{\alpha} + f\right)$$

$$\frac{dr}{dt} = \frac{ac}{\gamma} + ar - \alpha\left(\frac{ca}{\gamma\alpha} + \frac{c}{\gamma}f + \frac{a}{\alpha}r + rf\right)$$

$$\frac{dr}{dt} = \frac{ac}{\gamma} + ar - \frac{ac}{\gamma} - \frac{ac}{\gamma}f - ar - \alpha rf$$

$$= -\frac{ac}{\gamma}f - \alpha rf$$

For  $(r, f)$  the critical point is shifted to  $(0, 0)$

$$\begin{aligned} \frac{dF}{dt} &= -cF + \gamma RF \\ \frac{df}{dt} &= -c\left(\frac{a}{\alpha} + f\right) + \gamma\left(\frac{c}{\gamma} + r\right)\left(\frac{a}{\alpha} + f\right) \\ &= -\frac{ca}{\alpha} - cf + (c + \gamma r)\left(\frac{a}{\alpha} + f\right) \\ &= -\frac{ca}{\alpha} - cf + \frac{ca}{\alpha} + cf + \frac{\gamma a}{\alpha} r + \gamma rf \\ &= \frac{\gamma a}{\alpha} r + \gamma rf \end{aligned}$$

The linearized equations become

$$\frac{dr}{dt} = -\frac{\alpha c}{\gamma} f; \quad \frac{df}{dt} = \frac{\gamma a}{\alpha} r$$

$$\frac{d}{dt} \begin{pmatrix} r \\ f \end{pmatrix} = \begin{pmatrix} 0 & -\frac{\alpha c}{\gamma} \\ \frac{\gamma a}{\alpha} & 0 \end{pmatrix} \begin{pmatrix} r \\ f \end{pmatrix}$$

$$\lambda_1 = i\sqrt{ac}, \quad \lambda_2 = -i\sqrt{ac}$$

So

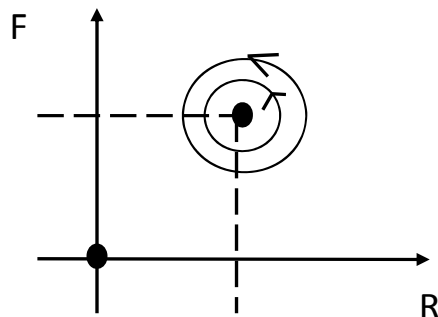
$$r = c_1 e^{i\sqrt{ac}t} + c_2 e^{-i\sqrt{ac}t}$$

$$f = c_3 e^{i\sqrt{ac}t} + c_4 e^{-i\sqrt{ac}t}$$

Eigenvalues of matrix

$$+\lambda^2 + \frac{\alpha c}{\gamma} \frac{\gamma a}{\alpha} = 0$$

$$\lambda = \pm i\sqrt{ac}$$



Both populations oscillate. If we solve for the coefficients we will see that, the rabbit population grows, which causes the fox population to grow.

Once the fox population gets high, the rabbit population begins to fall, followed by a drop in the fox population.

This cycle repeats itself.

