

# A Uniqueness Condition for Hyperbolic Systems of Conservation Laws

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**Abstract.** Consider the Cauchy problem for a hyperbolic  $n \times n$  system of conservation laws in one space dimension:

$$u_t + f(u)_x = 0, \quad u(0, x) = \bar{u}(x). \quad (CP)$$

Relying on the existence of a continuous semigroup of solutions, we prove that the entropy admissible solution of (CP) is unique within the class of functions  $u = u(t, x)$  which have bounded variation along a suitable family of space-like curves.

## 1 - Introduction.

Consider a hyperbolic system of conservation laws in one space dimension:

$$u_t + f(u)_x = 0. \quad (1.1)$$

The following standard conditions [11, 12] will be assumed throughout. The flux function  $f : \Omega \mapsto \mathbb{R}^n$  is smooth, in a neighbourhood  $\Omega \subset \mathbb{R}^n$  of the origin. Let  $A(u) = Df(u)$  be the Jacobian matrix of  $f$  at  $u$  and assume that  $A(u)$  is strictly hyperbolic, i.e. with real distinct eigenvalues:  $\lambda_1(u) < \dots < \lambda_n(u)$ . We can thus choose bases of right and left eigenvectors  $r_i(u)$ ,  $l_i(u)$ ,  $i = 1, \dots, n$ , normalized so that

$$|r_i| \equiv 1, \quad \langle l_i, r_j \rangle = \begin{cases} 1 & \text{if } i = j, \\ 0 & \text{if } i \neq j \end{cases} \quad (1.2)$$

for every indices  $i, j \in \{1, \dots, n\}$  and all  $u \in \Omega$ . For each  $i = 1, \dots, n$ , we assume that the  $i$ -th field is either linearly degenerate, so that

$$\nabla \lambda_i \cdot r_i(u) \doteq \lim_{h \rightarrow 0} \frac{\lambda_i(u + hr_i(u)) - \lambda_i(u)}{h} = 0 \quad \text{for every } u \in \Omega,$$

or genuinely nonlinear, so that

$$\nabla \lambda_i \cdot r_i(u) > 0 \quad \text{for every } u \in \Omega.$$

In this setting, it was proved in [2, 3, 6] that the system (1.1) admits a uniformly Lipschitz continuous semigroup of solutions  $S : \mathcal{D} \times [0, \infty[ \mapsto \mathcal{D}$ . Here  $\mathcal{D} \subset \mathbf{L}^1(\mathbb{R}; \mathbb{R}^n)$  is a closed, positively invariant domain, such that all functions with suitably small total variation lie in  $\mathcal{D}$ , and all functions in  $u \in \mathcal{D}$  have uniformly bounded variation. For a given initial condition

$$u(0, \cdot) = \bar{u} \in \mathcal{D}, \quad (1.3)$$

a way to establish the uniqueness of solutions to the Cauchy problem (1.1)-(1.3) is thus to prove that every entropy weak solution  $u = u(t, x)$  actually coincides with the semigroup trajectory:

$$u(t, \cdot) = S_t \bar{u} \quad (1.4)$$

for all  $t \geq 0$ . Regularity conditions which imply the identity (1.4) were introduced in [4, 5]. These conditions provide some control on the oscillation of  $u$  in a forward neighborhood of each given point  $(t, x)$ .

In the present paper we consider an alternative regularity condition, quite simple to state, and prove that it suffices to guarantee uniqueness.

**(A3) (Locally Bounded Variation)** For some  $\delta > 0$ , along every space-like curve  $t = \gamma(x)$ , with  $|dt/dx| \leq \delta$  almost everywhere, the total variation of  $u$  is locally bounded.

In other words, we require that, whenever  $t = \gamma(x)$  is a space-like curve satisfying

$$|\gamma(x) - \gamma(x')| \leq \delta|x - x'| \quad \text{for all } x, x',$$

then the total variation of the composed map  $x \mapsto u(\gamma(x), x)$  is bounded on bounded intervals.

For completeness, we restate below our basic assumptions on weak solutions and the Lax entropy conditions.

**(A1) (Conservation Equations)** The function  $u = u(t, x)$  is a weak solution of the Cauchy problem (1.1), (1.3), taking values within the domain  $\mathcal{D}$  of a Standard Riemann Semigroup  $S$ . More precisely,  $u : [0, T] \mapsto \mathcal{D}$  is continuous w.r.t. the  $\mathbf{L}^1$  distance. The initial condition (1.3) holds, together with

$$\iint (u\varphi_t + f(u)\varphi_x) dxdt = 0 \tag{1.5}$$

for every  $\mathcal{C}^1$  function  $\varphi$  with compact support contained inside the open strip  $]0, T[ \times \mathbb{R}$ .

**(A2) (Entropy Condition)** Let  $u$  have an approximate jump discontinuity at some point  $(\tau, \xi) \in ]0, T[ \times \mathbb{R}$ . More precisely, let there exists states  $u^-, u^+ \in \Omega$  and a speed  $\lambda \in \mathbb{R}$  such that, calling

$$U(t, x) \doteq \begin{cases} u^- & \text{if } x < \xi + \lambda(t - \tau), \\ u^+ & \text{if } x > \xi + \lambda(t - \tau), \end{cases} \tag{1.6}$$

there holds

$$\lim_{\rho \rightarrow 0^+} \frac{1}{\rho^2} \int_{\tau-\rho}^{\tau+\rho} \int_{\xi-\rho}^{\xi+\rho} |u(t, x) - U(t, x)| dxdt = 0. \tag{1.7}$$

Then, for some  $i = 1, \dots, n$ , one has the entropy inequality:

$$\lambda_i(u^-) \geq \lambda \geq \lambda_i(u^+). \tag{1.8}$$

With the above assumptions, one has:

**Theorem.** *Assume that the system (1.1) generates a Standard Riemann Semigroup  $S : \mathcal{D} \times [0, \infty[ \mapsto \mathcal{D}$ . Then, for every  $\bar{u} \in \mathcal{D}$ ,  $T > 0$ , the Cauchy problem (1.1), (1.3) has a unique weak solution  $u : [0, T] \mapsto \mathcal{D}$  satisfying the assumptions **(A1)**–**(A3)**. Indeed, these conditions imply (1.4) for all  $t \in [0, T]$ .*

A proof of the theorem will be given in Section 3, while in Section 2 we collect a number of preliminary estimates.

## 2 - Preliminary results.

Since  $\mathcal{D} \subset \mathbf{L}^1 \cap BV$ , for sake of definiteness we shall always work with right-continuous representatives, so that our functions  $w \in \mathcal{D}$  will satisfy  $w(x) = w(x+)$  for all  $x \in \mathbb{R}$ . Moreover, given a continuous map  $u : [0, T] \mapsto \mathcal{D}$ , we will identify it with the corresponding function of two variables  $u \in \mathbf{L}^1([0, T] \times \mathbb{R}; \mathbb{R}^n)$ , defined in the natural way.

**Lemma 1.** *Let  $u : [0, T] \mapsto \mathcal{D}$  satisfy **(A1)**. Then  $u$  is Lipschitz continuous w.r.t. the  $\mathbf{L}^1$  distance.*

**Lemma 2.** *Let  $u : [0, T] \mapsto \mathcal{D}$  satisfy **(A1)**. Then  $u \in BV([0, T[ \times \mathbb{R}; \mathbb{R}^n)$ . Moreover there exists a set  $\mathcal{N}$  of Lebesgue measure 0, containing the endpoints of the interval  $[0, T]$ , such that for every  $\tau \in [0, T] \setminus \mathcal{N}$  and every  $\xi \in \mathbb{R}$  the following holds. Either  $u$  is approximately continuous at  $(\tau, \xi)$ , i.e. (1.7) holds with  $U(t, x) = u(\tau, \xi-) = u(\tau, \xi+)$ , or  $u$  has a non-horizontal approximate jump discontinuity at  $(\tau, \xi)$ , so that (1.6) and (1.7) hold. In this latter case one has the additional relations*

$$\begin{aligned} u^- &= u(\tau, \xi-), \quad u^+ = u(\tau, \xi+), \\ \lambda \cdot [u^+ - u^-] &= f(u^+) - f(u^-). \end{aligned}$$

If  $u$  satisfies **(A2)**, then (1.8) holds for some  $i = 1, \dots, n$ .

A proof of Lemma 1 can be found in [4]. The first statement of Lemma 2 is a corollary of Lemma 1. For the proof of the other statements see [4, 5, 8].

The next two lemmas derive some local properties of  $u$ , implied by our the assumption **(A3)**.

**Lemma 3.** *Let  $u : [0, T] \mapsto \mathcal{D}$  satisfy **(A3)**. Fix  $\tau \in [0, T]$  and  $\varepsilon > 0$ . Then the set*

$$B_{\tau, \varepsilon} = \left\{ \xi \in \mathbb{R}; \quad \limsup_{t \rightarrow \tau+, x \rightarrow \xi} |u(t, x) - u(\tau, \xi)| > \varepsilon \right\} \quad (2.1)$$

has no limit points.

*Proof.* If the conclusion fails, then there exists a monotone sequence  $\{\xi_i\}$  of points in  $B_{\tau, \varepsilon}$ , converging to some limit point  $\xi_0$ . To fix the ideas, let the sequence be decreasing, the other case being entirely similar. For each  $i \geq 1$ , by the right continuity of the function  $x \mapsto u(\tau, x)$  one can find a point  $w_i \in ]\xi_i, \xi_{i-1}[$  such that  $|u(\tau, w_i) - u(\tau, \xi_i)| \leq \varepsilon/2$ . Next, let  $t_i > \tau$  and  $x_i \in ]w_{i+1}, w_i[$  satisfy the inequalities

$$\begin{aligned} |u(t_i, x_i) - u(\tau, \xi_i)| &\geq \varepsilon, \\ |t_i - \tau| &\leq \delta \cdot \max\{|x_i - w_i|, |x_i - w_{i+1}|\}. \end{aligned} \quad (2.2)$$

Define a space-like curve  $t = \gamma(x)$ , with  $x \in [\xi_0, \xi_1]$ , by setting

$$\gamma(x) = \begin{cases} \tau & \text{if } x = \xi_0 \text{ or } x \geq w_1, \\ t_i - (x - x_i) \frac{t_i - \tau}{w_i - x_i} & \text{if } x \in [x_i, w_i], \\ \tau + (x - w_{i+1}) \frac{t_i - \tau}{x_i - w_{i+1}} & \text{if } x \in [w_{i+1}, x_i]. \end{cases} \quad (2.3)$$

By (2.2),  $\gamma$  is Lipschitz continuous with Lipschitz constant  $\delta$ . Since  $|u(t_i, x_i) - u(\tau, w_i)| \geq \varepsilon/2$  for all  $i \geq 1$ , the total variation of the composed map  $x \mapsto u(\gamma(x), x)$  on the interval  $[\xi_0, \xi_1]$  is infinite. This contradicts the assumption **(A3)**, thus proving Lemma 3.

Throughout the following, we consider a fixed number  $\lambda^* \geq 1/\delta$ , strictly larger than the absolute values of all propagation speeds  $\lambda_i$  of the system (1.1).

**Lemma 4.** *Let  $u : [0, T] \mapsto \mathcal{D}$  satisfy **(A3)**. Then for each  $(\tau, \xi) \in ]0, T[ \times \mathbb{R}$*

$$\lim_{\substack{t \rightarrow \tau+, x \rightarrow \xi \pm \\ |x - \xi| > \lambda^*(t - \tau)}} u(t, x) = u(\tau, \xi \pm).$$

*Proof.* Suppose the conclusion of the lemma fails. To fix the ideas, assume that, for some  $(\tau, \xi_0) \in ]0, T[ \times \mathbb{R}$ , there exist decreasing sequences  $t_j \rightarrow \tau+$  and  $x_j \rightarrow \xi_0+$ , such that

$$|x_j - \xi_0| \geq \lambda^* |t_j - \tau|, \quad |u(t_j, x_j) - u(\tau, \xi_0)| \geq \varepsilon$$

for some  $\varepsilon > 0$  and every index  $j$ . The case  $x_j \rightarrow \xi_0-$  can be treated in the same way.

Define the sequence of points

$$w_i \doteq x_j + \frac{1}{\delta}(t_j - \tau)$$

and observe that  $w_j \rightarrow \xi_0+$  as  $j \rightarrow \infty$ . By possibly taking a subsequence, say  $\{(t_i, x_i)\}$ , we can assume that the corresponding  $w_i$  satisfy

$$x_i \in ]w_{i+1}, w_i[, \quad |t_i - \tau| \leq \delta \cdot \max\{|x_i - w_i|, |x_i - w_{i+1}|\} \quad \text{for all } i.$$

Now let  $\gamma$  be the space-like curve defined by (2.3). Since  $w_i \rightarrow \xi_0+$ , for every  $i$  large enough, we have  $|u(\tau, w_i) - u(\tau, \xi_0)| \leq \varepsilon/2$ , hence  $|u(t_i, x_i) - u(\tau, w_i)| \geq \varepsilon/2$ . Therefore, the total variation of the map  $x \mapsto u(\gamma(x), x)$  on the interval  $[\xi_0, w_1]$  is infinite, in contradiction with **(A3)**.

Next, we recall some useful estimates, valid for the trajectories of a Standard Riemann Semi-group  $S$ .

**Lemma 5.** *Let  $w : [0, T] \mapsto \mathcal{D}$  be Lipschitz continuous. Then for every interval  $[a, b] \in \mathbb{R}$  there holds:*

$$\begin{aligned} & \|w(T) - S_T w(0)\|_{\mathbf{L}^1([a+\lambda^*T, b-\lambda^*T]; \mathbb{R}^n)} \\ &= O(1) \cdot \int_0^T \left\{ \liminf_{h \rightarrow 0^+} \frac{\|w(\tau+h) - S_h w(\tau)\|_{\mathbf{L}^1([a+\lambda^*(\tau+h), b-\lambda^*(\tau+h)]; \mathbb{R}^n)}}{h} \right\} d\tau. \end{aligned} \quad (2.4)$$

Here and in the sequel, with the Landau symbol  $O(1)$  we denote a quantity whose absolute value satisfies a uniform bound, depending only on the system (1.1).

Before stating the local integral estimates valid for semigroup trajectories, we need to define two local approximate solutions of (1.1). Let  $w \in \mathcal{D}$  and fix a point  $\xi \in \mathbb{R}$ . Call  $\omega = \omega(t, x)$  the unique self-similar entropy solution of the Riemann problem

$$\omega_t + f(\omega)_x = 0, \quad \omega(0, x) = \begin{cases} w(\xi-) & \text{if } x < 0, \\ w(\xi+) & \text{if } x > 0. \end{cases}$$

For  $t \geq 0$ , let

$$U^\sharp(t, x) \doteq \begin{cases} \omega(t, x - \xi) & \text{if } |x - \xi| \leq \lambda^*t, \\ w(x) & \text{if } |x - \xi| > \lambda^*t. \end{cases}$$

Next, call  $\tilde{A} \doteq Df(w(\xi))$  the Jacobian matrix of  $f$  computed at  $w(\xi)$ . For  $t \geq 0$ , define  $U^\flat(t, x)$  to be the solution of the linear hyperbolic Cauchy problem with constant coefficients

$$U_t^\flat + \tilde{A}U_x^\flat = 0, \quad U^\flat(0) = w.$$

**Lemma 6.** *For every function  $w \in \mathcal{D}$ , every  $\xi \in \mathbb{R}$  and  $h, \rho > 0$ , with the above definitions one has*

$$\frac{1}{h} \int_{\xi-\rho+h\hat{\lambda}}^{\xi+\rho-h\hat{\lambda}} \left| (S_h w)(x) - U^\sharp(h, x) \right| dx = O(1) \cdot \text{Tot.Var.}\{w; ]\xi - \rho, \xi[ \cup ]\xi, \xi + \rho[ \}, \quad (2.5)$$

$$\frac{1}{h} \int_{\xi-\rho+h\hat{\lambda}}^{\xi+\rho-h\hat{\lambda}} \left| (S_h w)(x) - U^\flat(h, x) \right| dx = O(1) \cdot \left( \text{Tot.Var.}\{w; ]\xi - \rho, \xi + \rho[ \} \right)^2. \quad (2.6)$$

For the proofs of the two above lemmas, see [1]. We conclude this section by recalling two technical results, that will be needed toward a proof of our Theorem. The proofs can be found in [4].

**Lemma 7.** *Let  $w \in \mathbf{L}^1(]a, b[; \mathbb{R}^n)$  be such that for some Radon measure  $\mu$ , one has*

$$\left| \int_{\zeta_1}^{\zeta_2} w(x) dx \right| \leq \mu([\zeta_1, \zeta_2]), \quad \text{whenever } a < \zeta_1 < \zeta_2 < b.$$

Then

$$\int_a^b |w(x)| dx \leq \mu([a, b]).$$

**Lemma 8.** [4] *Let  $u : [0, T] \mapsto \mathcal{D}$  be Lipschitz continuous. At a given point  $(\tau, \xi)$ , let the conditions (1.6)-(1.7) hold, for some  $u^-, u^+ \in \mathbb{R}^n$ ,  $\lambda \in \mathbb{R}$ . Then, for each  $\tilde{\lambda} > 0$  one has*

$$\begin{aligned} \lim_{\rho \rightarrow 0^+} \sup_{|h| \leq \rho} \int_0^{\tilde{\lambda}} |u(\tau + h, \xi + \lambda h + \rho y) - u^+| dy &= 0, \\ \lim_{\rho \rightarrow 0^+} \sup_{|h| \leq \rho} \int_{-\tilde{\lambda}}^0 |u(\tau + h, \xi + \lambda h + \rho y) - u^-| dy &= 0. \end{aligned}$$

### 3 - Proof of the Theorem.

Let  $u$  satisfy **(A1)**–**(A3)**. To deduce (1.4), in view of Lemma 5 it suffices to show that for every interval  $[a, b] \subset \mathbb{R}$  and a.e.  $\tau \in [0, T]$  one has

$$\liminf_{h \rightarrow 0^+} \frac{\|u(\tau + h) - S_h u(\tau)\|_{\mathbf{L}^1([a, b]; \mathbb{R}^n)}}{h} = 0 \quad (3.1)$$

In fact, we will show that (3.1) is valid for every  $[a, b] \in \mathbb{R}$  whenever  $\tau \in [0, T] \setminus \mathcal{N}$ . The proof is divided in 3 steps. The aim of the first two steps is to derive the appropriate estimates on the error

$$\|u(\tau + h) - S_h u(\tau)\|_{\mathbf{L}^1(I; \mathbb{R}^n)},$$

when  $h > 0$  and the interval  $I \subset [a, b]$  are small enough. This will be done using the inequalities in Lemma 6, namely (2.5) near points where  $u(\tau, \cdot)$  has large variation, and (2.6) on intervals where the total variation of  $u(\tau, \cdot)$  is suitably small.

In the third step we construct a suitable covering of  $[a, b]$  and complete the proof of (3.1) combining the estimates obtained in steps 1 and 2.

**STEP 1.** Fix  $\varepsilon \geq 0$  and assume  $\tau \notin \mathcal{N}$ . Then, at every point  $\xi \in \mathbb{R}$  the limit (1.7) holds for some  $u^-, u^+, \lambda$ . Observe that  $u^+ = u^-$  at a point where  $u$  is approximately continuous, while  $u^+ \neq u^-$  if  $u$  has an approximate jump discontinuity at  $(\tau, \xi)$ . By (1.7), from Lemma 8 it follows

$$\begin{aligned} & \lim_{h \rightarrow 0^+} \frac{1}{h} \int_{\xi - \lambda^* h}^{\xi + \lambda^* h} |u(\tau + h, x) - U(\tau + h, x)| dx \\ & \leq \lim_{h \rightarrow 0^+} \frac{1}{h} \int_{\xi - \lambda^* h}^{\xi + \lambda^* h} |u(\tau + h, x) - u^+| dx + \lim_{h \rightarrow 0^+} \frac{1}{h} \int_{\xi - \lambda^* h}^{\xi + \lambda^* h} |u(\tau + h, x) - u^-| dx = 0. \end{aligned}$$

Hence

$$\frac{1}{h} \int_{\xi - \lambda^* h}^{\xi + \lambda^* h} \left| u(\tau + h, x) - U(\tau + h, x) \right| dx \leq \varepsilon$$

for all  $h > 0$  sufficiently small.

By Lemma 2,  $U(t, x) = U^\sharp(t - \tau, x)$  in a forward neighbourhood of the point  $(\tau, \xi)$ . Hence by (2.5) we get

$$\begin{aligned} \frac{1}{h} \int_{\xi - \lambda^* h}^{\xi + \lambda^* h} \left| u(\tau + h, x) - (S_h u(\tau))(x) \right| dx &\leq \varepsilon + \frac{1}{h} \int_{\xi - \lambda^* h}^{\xi + \lambda^* h} \left| (S_h u(\tau))(x) - U(\tau + h, x) \right| dx \\ &= \varepsilon + O(1) \cdot \text{Tot.Var.} \{ u(\tau); ]\xi - 2\lambda^* h, \xi[ \cup ]\xi, \xi + 2\lambda^* h[ \} \} \leq 2\varepsilon \end{aligned} \quad (3.2)$$

for  $h > 0$  small enough. Note that here the maximum size of  $h$  depends on  $\xi$ ,  $\tau$  and  $\varepsilon$ .

STEP 2. Fix  $\varepsilon > 0$  and an interval  $]c, d[ \subset \mathbb{R}$  centered at a point  $\xi$  and such that  $]c, d[ \cap B_{\tau, \varepsilon} = \emptyset$ . Here  $B_{\tau, \varepsilon}$  is the set (2.1) of points where the oscillation of  $u$  is  $> \varepsilon$ . Consider a family of trapezoids  $\{\Gamma_h\}_{h>0}$  defined as

$$\Gamma_h = \left\{ (s, x); \quad s \in [\tau, \tau + h], \quad x \in ]c + (s - \tau)\lambda^*, d - (s - \tau)\lambda^* [ \right\}.$$

We first show that for small  $h > 0$  and every  $(s, x) \in \Gamma_h$  one has

$$|u(s, x) - u(\tau, \xi)| \leq 2\varepsilon + \text{Tot.Var.} \{ u(\tau); ]c, d[ \} \quad (3.3)$$

Indeed, by Lemma 4 the inequality (3.3) clearly holds for points  $(s, x)$  contained in small neighbourhoods of the lower corner points  $(\tau, c)$  and  $(\tau, d)$ . It thus remains to prove (3.3) in a region of the form  $[\tau, \tau + h] \times [c + h', d - h']$ , with  $h' > 0$  given and for some  $h > 0$  suitably small. Since  $[c + h', d - h'] \cap B_{\tau, \varepsilon} = \emptyset$ , for every  $y \in [c + h', d - h']$  we can find  $h_y, \rho_y > 0$  such that (3.3) holds when  $(s, x) \in [\tau, \tau + h_y] \times ]y - \rho_y, y + \rho[$ . Covering the compact interval  $[c + h', d - h']$  with finitely many open intervals  $]y_j - \rho_{y_j}, y_j + \rho_{y_j}[$ ,  $j = 1, \dots, N$  and choosing  $h \doteq \min h_{y_j}$ , we obtain (3.3) for all  $(s, x) \in [\tau, \tau + h] \times [c + h', d - h']$ .

We now show that, for all  $h > 0$  with  $h < (d - c)/2\lambda^*$ , the following estimate holds:

$$\begin{aligned} &\int_{c + \lambda^* h}^{d - \lambda^* h} \left| u(\tau + h, x) - U^\flat(+h, x) \right| dx \\ &= O(1) \cdot \sup_{(s, x) \in \Gamma_h} |u(s, x) - u(\tau, \xi)| \cdot \int_{\tau}^{\tau + h} \text{Tot.Var.} \left\{ u(\tau); [c + \lambda^*(t - \tau), d - \lambda^*(t - \tau)] \right\} dt. \end{aligned} \quad (3.4)$$

To derive (3.4), we proceed as in [4]. For each  $i = 1, \dots, n$  call  $\tilde{\lambda}_i, \tilde{l}_i, \tilde{r}_i$  respectively the  $i$ -th eigenvalue and the left and right eigenvectors of the matrix  $\tilde{A} = Df(u(\tau, \xi))$ , normalized as in (1.2).



Let  $\zeta' < \zeta''$  belong to the interval  $]c + \lambda^*h, d - \lambda^*h[$ . We now need to estimate the quantities

$$E_i \doteq \int_{\zeta_1}^{\zeta_2} \left[ \tilde{l}_i(u(\tau + h, x) - U^b(h, x)) \right] dx.$$

Obviously

$$\tilde{l}_i U^b(h, x) = \tilde{l}_i U^b(0, x - \tilde{\lambda}_i h) = \tilde{l}_i u(\tau, x - \tilde{\lambda}_i h).$$

Integrating (1.1) over the domain

$$\left\{ (s, x); s \in [\tau, \tau + h], \zeta' + (s - \tau - h)\tilde{\lambda}_i \leq x \leq \zeta'' + (s - \tau - h)\tilde{\lambda}_i \right\},$$

we obtain

$$\begin{aligned} E_i &= \int_{\zeta'}^{\zeta''} \tilde{l}_i u(\tau + h, x) dx - \int_{\zeta'}^{\zeta''} \tilde{l}_i u(\tau, x - \tilde{\lambda}_i h) dx \\ &= \int_{\tau}^{\tau+h} \tilde{l}_i \cdot (f(u) - \tilde{\lambda}_i u)(t, \zeta' + (t - \tau - h)\tilde{\lambda}_i) dt \\ &\quad - \int_{\tau}^{\tau+h} \tilde{l}_i \cdot (f(u) - \tilde{\lambda}_i u)(t, \zeta'' + (t - \tau - h)\tilde{\lambda}_i) dt. \end{aligned} \tag{3.5}$$

Consider the states

$$u' \doteq u(t, \zeta' + (t - \tau - h)\tilde{\lambda}_i), \quad u'' \doteq u(t, \zeta'' + (t - \tau - h)\tilde{\lambda}_i), \quad \tilde{u} \doteq u(\tau, \xi)$$

and define the averaged matrix

$$A^* \doteq \int_0^1 \left[ Df(su'' + (1-s)u') - Df(\tilde{u}) \right] ds.$$

One can check that

$$\tilde{l}_i \left( f(u'') - f(u') - \tilde{\lambda}_i(u'' - u') \right) = \tilde{l}_i \left( Df(\tilde{u}) \cdot (u'' - u') - \tilde{\lambda}_i(u'' - u') \right) + \tilde{l}_i A^*(u'' - u') = \tilde{l}_i A^*(u'' - u').$$

Therefore

$$\left| \tilde{l}_i \left( f(u'') - f(u') - \tilde{\lambda}_i(u'' - u') \right) \right| = O(1) \cdot |u'' - u'| \cdot \|A^*\| = O(1) \cdot |u'' - u'| \cdot (|u'' - \tilde{u}| + |u' - \tilde{u}|).$$

Together with (3.5) this yields:

$$\begin{aligned} |E_i| &= O(1) \cdot \int_{\tau}^{\tau+h} \left\{ \left| u(t, \zeta' + (t - \tau - h)\tilde{\lambda}_i) - u(t, \zeta'' + (t - \tau - h)\tilde{\lambda}_i) \right| \cdot \right. \\ &\quad \left. \cdot \left( \left| u(t, \zeta' + (t - \tau - h)\tilde{\lambda}_i) - u(\tau, \xi) \right| + \left| u(t, \zeta'' + (t - \tau - h)\tilde{\lambda}_i) - u(\tau, \xi) \right| \right) \right\} dt \\ &= O(1) \cdot \sup_{(s,x) \in \Gamma_h} |u(s, x) - u(\tau, \xi)| \cdot \\ &\quad \cdot \int_{\tau}^{\tau+h} \text{Tot.Var.} \left\{ u(t); [\zeta' + (t - \tau - h)\tilde{\lambda}_i, \zeta'' + (t - \tau - h)\tilde{\lambda}_i] \right\} dt. \end{aligned}$$

Therefore

$$\begin{aligned}
& \left| \int_{\zeta'}^{\zeta''} \left[ u(\tau + h, x) - U^b(h, x) \right] dx \right| \leq \sum_{i=1}^n |E_i| \\
& = O(1) \cdot \sup_{(s,x) \in \Gamma_h} |u(s, x) - u(\tau, \xi)| \cdot \\
& \quad \cdot \int_{\tau}^{\tau+h} \left[ \sum_{i=1}^n \text{Tot.Var.} \left\{ u(t); ]\zeta' + (t - \tau - h)\tilde{\lambda}_i, \zeta'' + (t - \tau - h)\tilde{\lambda}_i \right\} \right] dt.
\end{aligned}$$

In view of Lemma 7, this establishes (3.4).

Combining (3.3), (3.4) and (2.6) we obtain

$$\begin{aligned}
& \int_{c+\lambda^*h}^{d-\lambda^*h} \left| u(\tau + h, x) - (S_h u(\tau))(x) \right| dx \\
& = O(1) \cdot \left( 2\varepsilon + \text{Tot.Var.} \left\{ u(\tau); ]c, d[ \right\} \right) \cdot \int_{\tau}^{\tau+h} \text{Tot.Var.} \left\{ u(t); [c + (t - \tau)\lambda^*, d - (t - \tau)\lambda^*] \right\} dt \\
& \quad + O(1) \cdot h \cdot \left( \text{Tot.Var.} \left\{ u(\tau); ]c, d[ \right\} \right)^2,
\end{aligned} \tag{3.6}$$

valid for small  $h > 0$ .

STEP 3. Fix  $\varepsilon > 0$ , a time  $\tau \in [0, T] \setminus \mathcal{N}$  and an interval  $[a, b] \subset \mathbb{R}$ . By Lemma 3, the set  $B_{\tau, \varepsilon} \cap [a, b]$  contains finitely many points, say  $\xi_1 < \xi_2 < \dots < \xi_N$ . Observe that every point  $\xi$  where  $u(\tau, \cdot)$  has a jump  $> \varepsilon$  is certainly included in the above list.

We can now cover the set  $[a, b] \setminus \{\xi_1, \dots, \xi_N\}$  with open intervals  $]c_\alpha, d_\alpha[$ ,  $\alpha = 1, \dots, M$ , satisfying the following conditions:

- (i)  $\{\xi_1, \dots, \xi_N\} \cap \bigcup_{\alpha=1}^M ]c_\alpha, d_\alpha[ = \emptyset$ ,
- (ii)  $\text{Tot.Var.} \left\{ u(\tau); ]c_\alpha, d_\alpha[ \right\} \leq 2\varepsilon$  for every  $\alpha = 1, \dots, M$ ,
- (iii) every point of  $[a, b]$  is contained in at most two distinct intervals  $]c_\alpha, d_\alpha[$ .

By steps 1 and 2, for every  $h > 0$  small enough one has

$$\begin{aligned}
& \frac{1}{h} \int_{\xi_i - \lambda^*h}^{\xi_i + \lambda^*h} \left| u(\tau + h, x) - (S_h u(\tau))(x) \right| dx \leq \frac{\varepsilon}{N}, \\
& \int_{c_\alpha + \lambda^*h}^{d_\alpha - \lambda^*h} \left| u(\tau + h, x) - (S_h u(\tau))(x) \right| dx \\
& = O(1) \cdot \varepsilon \cdot \int_{\tau}^{\tau+h} \text{Tot.Var.} \left\{ u(t); ]c_\alpha + (t - \tau)\lambda^*, d_\alpha - (t - \tau)\lambda^* [ \right\} dt \\
& \quad + O(1) \cdot h\varepsilon \cdot \text{Tot.Var.} \left\{ u(\tau); ]c_\alpha, d_\alpha[ \right\}
\end{aligned}$$

for every  $i = 1, \dots, N$  and every  $\alpha = 1, \dots, M$ . Finally,

$$\begin{aligned}
& \frac{1}{h} \int_a^b \left| u(\tau + h, x) - (S_h u(\tau))(x) \right| dx \\
& \leq \sum_{i=1}^N \frac{1}{h} \int_{\xi_i - \lambda^* h}^{\xi_i + \lambda^* h} \left| u(\tau + h, x) - (S_h u(\tau))(x) \right| dx + \sum_{\alpha=1}^M \frac{1}{h} \int_{c_\alpha + \lambda^* h}^{d_\alpha - \lambda^* h} \left| u(\tau + h, x) - (S_h u(\tau))(x) \right| dx \\
& \leq \varepsilon + O(1) \cdot \frac{\varepsilon}{h} \int_\tau^{\tau+h} \text{Tot.Var.}\{u(t); \mathbb{R}\} dt + O(1) \cdot \varepsilon \cdot \text{Tot.Var.}\{u(\tau); \mathbb{R}\} \\
& = O(1) \cdot \varepsilon.
\end{aligned}$$

Letting  $\varepsilon \rightarrow 0$  we obtain (3.1).

We have thus shown that if  $u$  satisfies **(A1)**–**(A3)**, then it must coincide with the corresponding semigroup trajectory  $t \mapsto S_t \bar{u}$ . On the other hand, one can easily check that the assumptions **(A1)**–**(A3)** are satisfied by all semigroup trajectories, because these are obtained as limits of wave-front tracking approximations. The proof of the Theorem is thus completed.

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