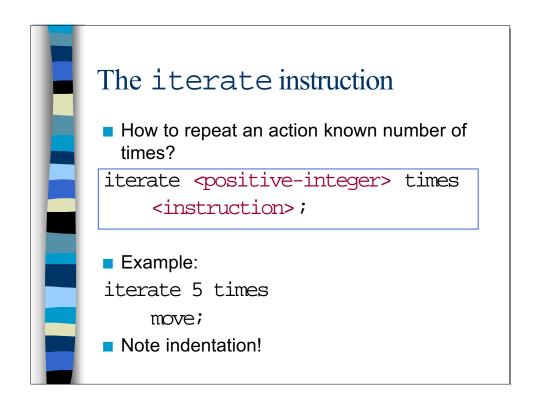
# IS12 - Introduction to Programming Lecture 5: Loops Peter Brusilovsky http://www2.sis.pitt.edu/~peterb/0012-051/



### iterate instruction with a block

- Semantics of execution
  - A sequence of instructions from instruction-1
     to instructionk will executed positive integer times. After that next-instruction

#### Example 1: Square Dance Old way New way beginning-of-program beginning-of-execution beginning-of-program move; beginning-of-execution turnleft; iterate 4 times begin move; turnleft; move; turnleft; move; turnleft; end; turnoff; move; end-of-execution turnleft; end-of-program turnoff; end-of-execution end-of-program

#### Problem 3.10: Nested Loops beginning-of-program **Explicit** Implicit = define-new-instruction plant-4 beginning-of-program iterate 3 times begin beginning-of-execution putbeeper; iterate 4 times begin move; iterate 3 times begin end; putbeeper; beginning-of-execution iterate 4 times begin move; plant-4; end; turnleft; turnleft; end; end; turnoff; turnoff; end-of-execution end-of-execution end-of-program end-of-program

#### Old way: Cleaner Stairs beginning-of-program define-new-instruction pickbeeper-if-present as define-new-instruction if next-to-a-beeper then turnright as begin pickbeeper; turnleft; turnleft; beginning-of-execution climb-stair; turnleft; pickbeeper -if-present; end; climb-stair; define-new-instruction pickbeeper -if-present; climb-stair as begin climb-stair; pickbeeper -if-present; turnleft; turnoff; move; end-of-execution turnright; end-of-program move; end;

# New Way: Cleaner Stairs 2

#### Is iterate always good?

```
beginning-of-program
  define-new-instruction
  turnright as
    iterate 3 times
       turnleft;

  define-new-instruction climb-
  stair as begin
      turnleft;
      move;
      turnright;
      move;
  end;
```

```
define-new-instruction
   pickbeeper-if-present as
   if next-to-a-beeper then
      pickbeeper;

beginning-of-execution
   iterate 3 times begin
      climb-stair;
      pickbeeper-if-present;
   end;
   turnoff;
end-of-execution
end-of-program
```

# Old way: Carpet (problem 3.8)

```
beginning-of-program
   define-new-instruction
   laycarpet as begin
     move;
     putbeeper;
     move;
     putbeeper;
     move;
     putbeeper;
     move;
     putbeeper;
     move;
     putbeeper;
     move;
     putbeeper;
     move;
      putbeeper;
```

```
beginning-of-execution
    laycarpet;
    turnleft;
    laycarpet;
    turnleft;
    laycarpet;
    turnleft;
    laycarpet;
    turnleft;
    laycarpet;
    turnoff;
    end-of-execution
end-of-program
```

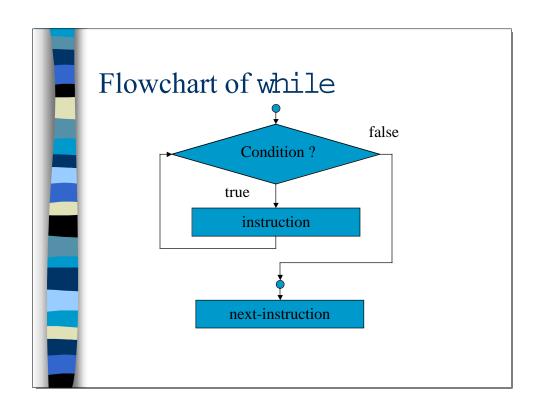
# New way: Carpet (problem 3.8)

```
beginning-of-program

define-new-instruction
laycarpet as
iterate 7 times begin
move;
putbeeper;
end;
beginning-of-execution
iterate 4 times begin
laycarpet;
turnleft;
end;
turnoff;
end-of-execution
end-of-program
```

# while loop

- Semantics of execution
  - While condition is true instruction is executed over and over.
  - After that next-instruction
  - What if it is wrong right away?



# 

# Examples

#### Find beeper

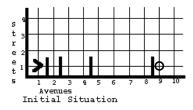
define-new-instruction go-to-beeper as while not-next-to-a-beeper do move;

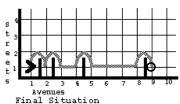
#### Get all beepers

define-new-instruction clear-corner-of-beepers as while next-to-a-beeper do pickbeeper;

# Case 1: Long Race to a Beeper

- Move Karel through a row of "hurdles"
- Each pair of Avenues may or may not have a hurdle between them
- The race is arbitrary long
- There is a beeper at the end of the course





# Solution: Long Race to a Beeper

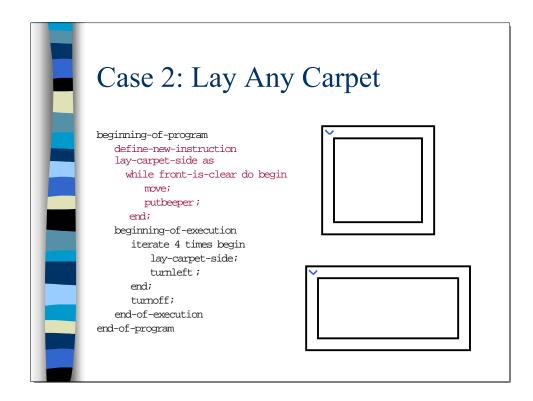
# Main program: beginning-of-execution while not-next-to-abeeper do race-stride; pickbeeper; turnoff; end-of-execution

#### Main subtask:

```
define-new-instruction
race-stride as
if front-is-clear then
move
else
jump-hurdle;
```

# Solution 2: Race to a Beeper

```
Decomposing jump-hurdle:
                             define-new-instruction
                                jump-up as begin
                                turnleft;
define-new-instruction
  jump-hurdle as begin
                               move;
                                turnright;
  jump-up;
                             end;
  move;
  jump-down;
                             define-new-instruction
                                jump-down as begin
end;
                                turnright;
                                move;
                                turnleft;
                             end;
```

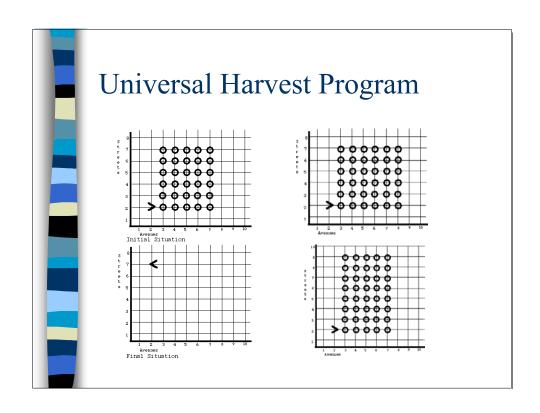


# Steps of Building a While loop

- What should be true when Karel has to finish the loop?
- Use opposite condition for while test
- "Frame" the while do what you need before/after to solve the problem
- Do the minimum what is needed to ensure that the loop eventually stops

## Loop Invariant and Changes

- At the beginning of every iteration:
  - What is always the same some condition that is true when we need to execute the loop body and false when we do not need to do it anymore?
  - What is different for each subsequent iteration that makes the new situation closer to the solution than previous?



# Original Solution for Harvest

```
beginning-of-program
                                                   define-new-instruction harvest-1-row as
   define-new-instruction turnright
                                                          pickbeeper; move;
   as begin
                                                          pickbeeper; move;
          turnleft;
                                                          pickbeeper; move;
          turnleft;
                                                          pickbeeper; move;
           turnleft;
                                                          pickbeeper;
                                                   define-new-instruction harvest-2-rows
   define-new-instruction
   qo-to-next-row as begin
                                                          harvest-1-row;
          turnleft;
                                                          go-to-next-row;
          move;
                                                          harvest-1-row;
          turnleft;
                                                   beginning-of-execution
   define-new-instruction position-
                                                          harvest-2-rows;
   for-next as begin
                                                          position-for-next;
          turnright;
                                                          harvest-2-rows;
                                                          position-for-next;
           turnright;
                                                          move;
                                                          tumoff;
                                                   end-of-execution
                                               end-of-program
```

# While Loops in Harvest

beginning-of-execution // at the beginning of every // iteration Karel stands at // the beginning of the next // double row facing east while next-to-a-beeper do begin harvest-1-row; go-to-next-row; harvest-1-row; position-for-next; end; position-for-next; move; turnoff; end-of-execution

- What is true at the beginning of every iteration?
  - at the beginning of every iteration Karel stands at the beginning of the next double row facing east
- What is different for each subsequent iteration that makes it closer to the solution?
- How we had to "frame" this loop?

# While Loops in Harvest

```
define-new-instruction harvest-
   1-row as begin
        while next-to-a-beeper
        do begin
            pickbeeper;
            move;
        end;
        step-back;
define-new-instruction step-
   back as begin
        turnleft;
        turnleft;
        move;
        turnleft;
        turnleft;
end;
```

- What is true at the beginning of every iteration?
- What is different for each subsequent iteration that makes it closer to the solution?
- How we had to "frame" this loop?

#### Before next lecture:

- Do reading assignment
  - Pattis: Chapter 5
  - Tutorial: lessons 8, 11
- Run Classroom Examples
- Check yourself by doing any 3 from exercises 4-13 from Section 5.9
- HW3 is due on 9/23/04