

General 2 unit problem

(1)

Let $x_j \in \mathbb{R}^n$ $f_j: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$\dot{x}_1 = f_1(x_1, x_2) \quad \dot{x}_2 = f_2(x_1, x_2)$$

want same eqns if $x_1 \leftrightarrow x_2$

$$\dot{x}_2 = f_1(x_2, x_1) \quad \dot{x}_1 = f_2(x_2, x_1)$$

$$\Leftrightarrow f_1(x_2, x_1) = f_2(x_1, x_2)$$

So:

$$\dot{x}_1 = f(x_1, x_2), \quad \dot{x}_2 = f(x_2, x_1)$$

Let $f(u, u) = 0$ + Let

$$A = \partial_1 f(u, u), \quad B = \partial_2 f(u, u)$$

$$\dot{y}_1 = Ay_1 + By_2, \quad \dot{y}_2 = Ay_2 + By_1$$

To see symmetry:

$$\text{Let } y_d = y_1 - y_2, \quad y_s = y_1 + y_2$$

$$\begin{aligned} \dot{y}_d &= \dot{y}_1 - \dot{y}_2 = Ay_1 + By_2 - (Ay_2 + By_1) \\ &= A(y_1 - y_2) + B(y_2 - y_1) \\ &= (A - B)y_d \end{aligned}$$

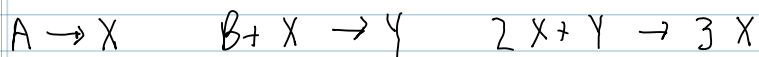
$$\dot{y}_s = (A + B)y_s \quad \text{so reduce to 2 nxn instead of 1 2nx2n!}$$

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You need only look at spectrum of smaller system.

Example: The Brusselator chemical reaction

This is the canonical reaction ~~pattern~~ for oscillations + pattern formation.



$X \rightarrow E$ all have rate 1 for simplicity

A B are fixed E doesn't matter

4 reactions $R_1 = A$ $R_2 = BX$ $R_3 = X^2Y$

$$R_4 = X$$

$$\dot{X} = R_1 - R_2 - 2R_3 + 3R_3 - R_4$$

$$\dot{Y} = R_2 - R_3$$

So $\frac{dx}{dt} = A - (b+1)x + x^2y \equiv f(x,y)$ $\frac{dy}{dt} = Bx - x^2y \equiv g(x,y)$

$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \leftrightarrow \begin{bmatrix} x_2 \\ y_2 \end{bmatrix}$
 $\begin{matrix} x_2 \xrightarrow{D_x} y_1 \\ y_1 \xrightarrow{D_x} x_2 \end{matrix}$
 + sim for y

$$\frac{dx_1}{dt} = f(x_1, y_1) + D_x(x_2 - x_1) \equiv F_1\left(\begin{bmatrix} x_1 \\ y_1 \end{bmatrix}, \begin{bmatrix} x_2 \\ y_2 \end{bmatrix}\right)$$

$$\frac{dy_1}{dt} = g(x_1, y_1) + D_y(y_2 - y_1)$$

Note $F_1(\vec{x}_1, \vec{x}_2) = F_2(\vec{x}_2, \vec{x}_1)$ so

Symmetry holds.

Fixed points $x_1 = x_2 = u$ $y_1 = y_2 = v$

$$A - (b+1)u + u^2v = 0 \quad Bu - u^2v = 0$$

Add together to get $A - u = 0 \Rightarrow u = A$
Then $v = B/A$.

With abuse of notation, let me call these a, b instead.

Matrix $A = \begin{bmatrix} \frac{\partial f - D_x \frac{\partial f}{\partial y}}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g - D_y \frac{\partial g}{\partial x}}{\partial y} \end{bmatrix}$ $B = \begin{bmatrix} D_x & 0 \\ 0 & D_y \end{bmatrix}$

So... $\frac{\partial f}{\partial x} = -(b+1) + 2xy$ $\frac{\partial f}{\partial y} = x^2$

$\frac{\partial g}{\partial x} = b - 2xy$ $\frac{\partial g}{\partial y} = -x^2$

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$$\text{So } A = \begin{bmatrix} b-1-D_x & a^2 \\ -b & -a^2-D_y \end{bmatrix} \quad B = \begin{bmatrix} D_x & 0 \\ 0 & D_y \end{bmatrix}$$

$$A+B = \begin{bmatrix} b-1 & a^2 \\ -b & -a^2 \end{bmatrix} \equiv M_S \quad \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$A-B = \begin{bmatrix} b-1-2D_x & a^2 \\ -b & -a^2-2D_y \end{bmatrix} \equiv M_D \quad \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\boxed{\text{Tr } M_S = b-a^2-1 \quad \text{Det } M_S = a^2 > 0}$$

$$\text{Tr } M_D = b-a^2-1 - 2(D_x+D_y)$$

$$\text{Det } M_D = a^2 - 2[D_y(b-1) - D_x a^2] + 4 D_x D_y$$

$$\text{Tr } M_D < 0 \Rightarrow \text{Tr } M_D < 0$$

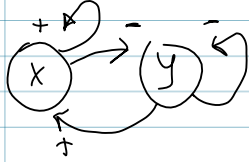
(Can M_D ever be negative?)

What does M_D mean?

$$\text{Assume } \text{Tr } M_S < 0 \Rightarrow a^2 > b-1$$

$$\text{Necessary condition for } \text{Det } M_D < 0 \quad \Delta$$
$$D_y(b-1) - D_x a^2 > 0 \Rightarrow \boxed{b-1 > 0} \quad \dagger$$

$$\Rightarrow D_y > D_x \frac{a^2}{b-1} > D_x \text{ since } a^2 > b-1$$



Diffusion of X < Diff Y

Exam Suppose $D_x = 0$ Then choose D_y large enough so that

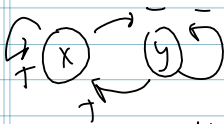
$$a^2 - 2D_y(b-1) < 0$$

Then for small enough D_x can be stabilized
The uniform state!

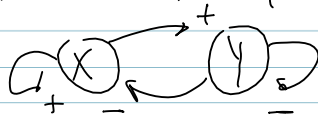
More generally for 2 dimensional coupled system with Diffusion:

$$A = \begin{bmatrix} a - D_x & \beta \\ \delta & \delta - D_y \end{bmatrix} \quad B = \begin{bmatrix} D_x & 0 \\ 0 & D_y \end{bmatrix}$$

Two classes of interaction dynamics:



Positive feedback



Act-inhibitor

(HW) provide $\begin{bmatrix} - & + \\ - & + \end{bmatrix}$ can never have
diffusive pattern formation!

(Note $\begin{pmatrix} - & - \\ + & + \end{pmatrix}$ is same since diagonal product is all that comes out)

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Hw Numerically explore Brusselator
for

Hw Let $a = 0.6$, $b = 1.25$.

- Find a curve in (D_x, D_y) st $\det M_D = 0$

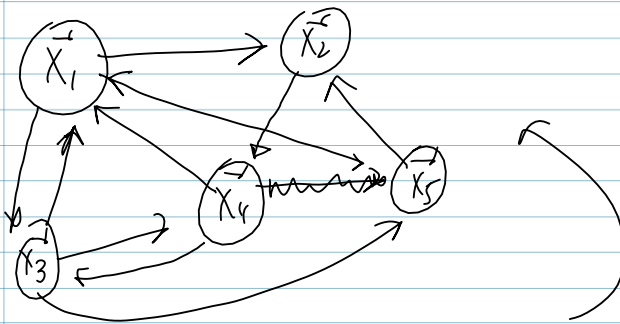
- Pick (D_x, D_y) st $\det M_D < 0$ &
numerically solve ODE \rightarrow 5 low max
There are equilibria st $X_1 \neq X_2$

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We have studied the case of a ~~single~~ pair of coupled cells.

How much can this be generalized?

Let's say we have N "cells"



and coupling between them that is the same form of coupling but not necessarily to any element

Furthermore, suppose that each cell has same number of arrows going into it

Since coupling is the same to every one and have same # arrows, this means that there is symmetry in the sense that if we start with $X_1 = X_2 = \dots = X_n$ then this is invariant!

The homogeneous solution is a solution

Let's look at the linearization of this system

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Let \vec{e} be eigenvector of Q and λ be the corresponding eigenvalue

① Note that $\lambda = 2$ and $\vec{e} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$ is

the symmetric eigenvalue.

② Note $A \rightarrow A - 2B$ for ditensive type coupling

Because of M_{ij} symmetry, we can reduce M_{ij} ~~max~~ 5×5 system to

5×5 systems.

Claim eigenvalues of M are eigenvalues of $A + \lambda_j B$ $j=1, \dots, 5$

Proof (Claim) Let $\begin{pmatrix} e_1 \\ e_2 \\ e_3 \\ e_4 \\ e_5 \end{pmatrix}$ be eigen components of eigenvector with eigenvalue λ of Q

$$Q \vec{e} = \lambda \vec{e}$$

$$\text{Let } \vec{v} = \begin{pmatrix} \vec{u} e_1 \\ \vec{u} e_2 \\ \vdots \\ \vec{u} e_5 \end{pmatrix}$$

$$\vec{u} \in \mathbb{R}^n$$

$$M \vec{v} = \begin{bmatrix} A \vec{u} e_1 + B \vec{u} e_3 + B \vec{u} e_5 \\ B \vec{u} e_1 + A \vec{u} e_2 + B \vec{u} e_5 \\ \vdots \\ \vdots \end{bmatrix}$$

$$\text{Note } e_3 + e_5 = \lambda e_1$$

$$e_1 + e_5 = \lambda e_2 \quad \text{since eigenvector of } Q$$

\vdots

$$\vec{M} \vec{v} = \begin{bmatrix} (A + \lambda B) \vec{u} \\ (A + \lambda B) \vec{u} \end{bmatrix}$$

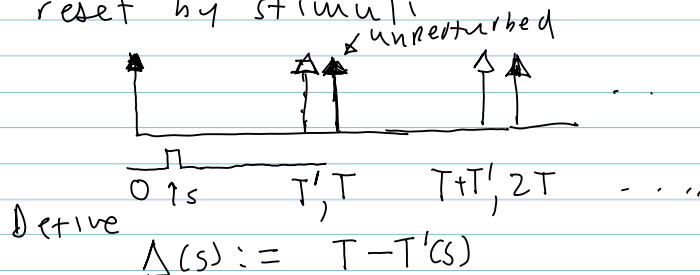
So eigenvalues of \vec{M} are found by solving $(A + \lambda_j B) \vec{u} = 0$ eigenvalue problem $j = 1, \dots, S$

Nothing special about all the "1's" in Q could be arbitrary

Application: pulse coupled oscillators

Consider a firefly. He flashes periodically with frequency ω . With no flash, he is able to communicate to other fireflies

Aside Limit cycle oscillators can be reset by stimuli



called phase resetting curve.

Let θ_j be the phase of j th insect (defined mod T)

Let $P(\theta)$ be the pulse of light emitted by the firefly.

$$\frac{d\theta_j}{dt} = \omega_j + \left[\sum_{k=1}^N g_{jk} P(\theta_k) \right] \Delta(\theta_j)$$

\uparrow Firefly frequency \uparrow Input from other FF's \uparrow response function

Simplification: $\omega_j = \omega \quad \forall j$ (identical)
 $\sum_{j=1}^N g_{jk} = g \quad \forall j$ Let $T = 2\pi$

Synchrony: $\theta_j(t) \equiv \theta(t) \quad \forall j$

$$\frac{d\theta}{dt} = \omega + g P(\theta) \Delta(\theta)$$

Assume $\omega + g P(\theta) \Delta(\theta) > 0$ for all θ

This means $\dot{\theta} > 0$ and period is:

$$\int_0^{2\pi} \frac{d\theta}{\omega + g P(\theta) \Delta(\theta)} = P_0 = \text{period}$$

Is synchrony stable?

Let's look at the linearization around

$$\theta_j(t) = \bar{\theta}(t)$$

$$\dot{Y}_j = \Delta(\theta(t)) \sum_{k=1}^N g_{jk} p'(\theta(t)) Y_k(t) + g \Delta'(\theta(t)) p(\theta(t)) Y_j(t)$$

Using the theory above, let λ_1 be an eigenvalue of the matrix G . Note $\lambda_1 = g$.

$$\vec{Y} = u(t) \vec{e} +$$

$$\dot{u} = [\Delta(\theta(t)) \lambda_1 p'(\theta(t)) + g \Delta'(\theta(t)) p(\theta(t))] u$$

$$\stackrel{P_0}{=} \alpha(t) u(t)$$

If $\int_0^t \alpha(s) ds > 0$ then unstable since

$$u(t) = u(0) e^{\int_0^t \alpha(s) ds}$$

Let us do a little calculation.

$$\dot{\theta} = \omega + g p(\theta) \Delta(\theta)$$

$$\ddot{\theta} = [g p'(\theta) \Delta(\theta) + g p(\theta) \Delta'(\theta)] \dot{\theta}$$

Since $\dot{\theta}$ is periodic, we have

$$g \int_0^{P_0} p'(\theta(t)) \Delta(\theta(t)) + p(\theta(t)) \Delta'(\theta(t)) dt = 0!$$

so this means

$$\int_0^{P_0} p'(\theta(t)) \Delta(\theta(t)) dt = - \int_0^{P_0} p(\theta(t)) \Delta'(\theta(t)) dt$$

$$\text{Thus} \quad \int_0^{p_0} \alpha(s) ds = (g - \lambda_e) \int_0^{p_0} p(\theta(t)) \Delta'(\theta(t)) dt$$

Suppose all entries of G are positive.

Then F.P. $\Rightarrow \operatorname{Re}(g - \lambda_e) > 0$ since

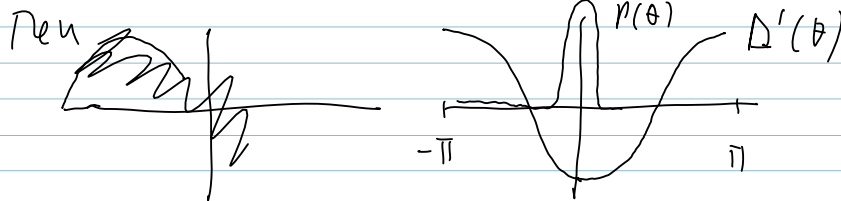
$|g| > |\lambda_e|$ ($\lambda \neq 1$) & $g > 0$ is real.

If $\int_0^{p_0} p(\theta(t)) \Delta'(\theta(t)) dt < 0$ Then

g such ω stable. For Fireflies

$\Delta(\theta) \sim -\sin \theta$ so $\Delta'(\theta) = -\cos \theta$

If $p(\theta)$ is centered around 0 & positive



Integral will be negative!