

Beyond pattern formation instabilities

- The standard model for field equations

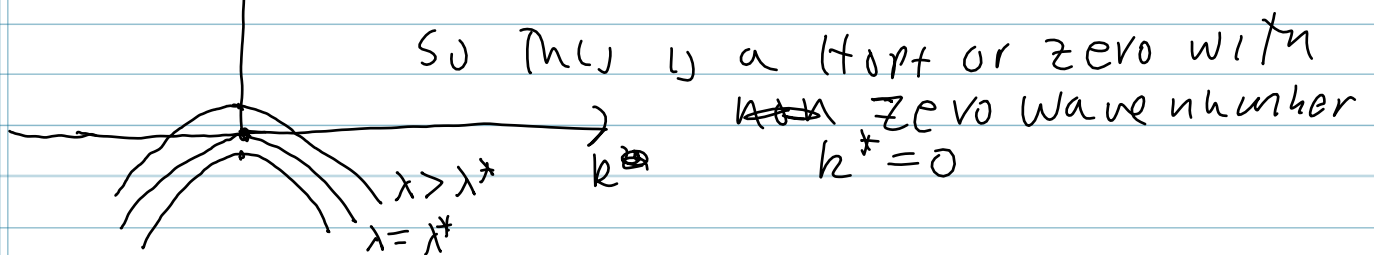
I will start with a reaction-diffusion example and try to derive a classic model from this, the Ginzburg-Landau equation.

$$\frac{\partial u}{\partial t} = F(u, \lambda) + D \frac{\partial^2 u}{\partial x^2} \quad -\infty < x < \infty.$$

and I will work on the infinite domain

We suppose that  $u_0(\lambda)$  is an equilibrium point and that we have the following picture:  $\tilde{\nu}(\lambda, k^2)$  is maximal eigenvalue (in real part sense)

$F$



Typically we ignore space completely since eigen space is either

$$z e^{i\omega t} \vec{z}, \text{ or } r \vec{z}$$

with  $z = z(\tau)$ ,  $r = r(\tau)$ ,  $\tau = \varepsilon^2 t$  or  $\varepsilon t$

But clearly, space exists in this model so how do we incorporate it.

For simplicity, suppose it is a Hopf bifurcation, so that in absence of space, we have:

$$z_t = z(\alpha(\lambda - \lambda^*) - \beta z \bar{z}) \quad (\star \star)$$

We have already figured out how to compute  $\alpha, \beta$ .

Let us alter our ansatz. Note that for  $\lambda > \lambda^*$ ,  $|\lambda|$  small but non zero ~~perturbation~~ leads to instability & growth. Thus we will assume that there are "long wave" effects and may look for patterns that depend on slow modulations in space. Let's introduce a spatial effect

$$z = \varepsilon X$$

$$\text{so that } \frac{\partial^2}{\partial X^2} = \varepsilon^2 \frac{\partial^2}{\partial z^2}$$

~~Without belaboring the calculations, we get a new term in our perturbation.~~

We suppose that ~~instead of~~

$$u(x,t) = \varepsilon z(\tau, \zeta) e^{i\omega_0 t} \vec{\zeta} + \text{cc} + \varepsilon^2 u_2 + \varepsilon^3 u_3 + \dots$$

Without belaboring calculations, we get a new term in the  $O(\varepsilon^3)$  equations:

$$z_t e^{i\omega_0 t} \vec{\zeta} = A_0 u_3 - \frac{du_3}{dt} + \dots + D \vec{\zeta} z_{\zeta\zeta} e^{i\omega_0 t}$$

Nonlinear stuff  $\rightarrow$

so that when we apply the Fredholm Alt we get the spatial analogue of  $(\star \star)$

$$\frac{\partial z}{\partial t} = z(\alpha(\lambda - \lambda^*) - \beta z \bar{z}) + d z_{33} \quad (2)$$

Where  $d = \bar{\eta}^T D \zeta$

We can now prove that if the picture is as in F, that  $\text{Re } d > 0$ .

To see why this is, note that

$$\text{Re } \tilde{V}(k^2) \approx -B k^2 \text{ at } \lambda = \lambda^* \text{ by hypothesis (see Figure) where } B > 0$$

Let  $A_0 - k^2 D \equiv M(k^2)$  and we will examine  $\tilde{V}(k^2)$  for  $k^2$  small

write  $M(k^2) \phi(k^2) = \tilde{V}(k^2) \phi(k^2)$

differentiate wrt  $k^2$ :  $\phi_0 = \tilde{V}'$

$$-D \phi_0 + A_0 \phi' = i \omega_0 \phi' \Rightarrow B \phi_0 + i C \phi_0$$

multiply by  $\bar{\eta}^T$  to get

$$d \equiv \bar{\eta}^T D \zeta = B - i C$$

So  $\text{Re } d > 0$ .

Equation (2) is called complex Ginzberg-Landau equation or CGL

Let me absorb  $\lambda - \lambda^*$  into  $\alpha$  and write  $\alpha = a_1 + i a_2$ ,  $\beta = b_1 - i b_2$ ,  $d = d_1 + i d_2$

$$z = r e^{i\theta}$$

$$r_t = (a_1 - b_1 r^2) r + d_1 (r_{33} - r \theta_3^2) - d_2 (2r_3 \theta_3 + r \theta_{33})$$

$$\theta_t = a_2 + b_2 r^2 + d_1 (\theta_{33} + \frac{2r_3 \theta_3}{r}) + d_2 (\frac{r_{33}}{r} - \theta_3^2)$$

Even when  $d_2 = 0$ , this equation has many interesting solutions (most of which are dynamically unstable)

Let's explore some of them.

$$\text{Let } r = \rho \quad \theta(z, t) = \Omega t + \alpha z$$

Plug this in and we get:

$$0 = \rho(a_1 - b_1 \rho^2) - d_1 \rho \alpha^2$$

$$\Rightarrow \rho = \frac{\sqrt{a_1 - d_1 \alpha^2}}{b_1} \quad (3)$$

$$\Omega = a_2 + b_2 \rho^2 - d_2 \alpha^2 \quad (4)$$

This is a family of traveling waves. When  $\alpha = 0$ , we have the synchronous spatial oscillation, but for  $\alpha \neq 0$ , we get nice traveling waves.

Notice that since  $d_1 \geq 0$ ,  $b_1 > 0$ ,  $a_1 > 0$  as  $\alpha$  increases amplitude decreases and thus, they exist for a limited band of  $\alpha$ .

Combining (3) & (4) we get:

$$\Omega = a_2 + \frac{a_1 b_2}{b_1} - \left(d_2 + \frac{b_2 d_1}{b_1}\right) \alpha^2$$

The so-called dispersion relation.

Stability is a bitch, but we will try to get some insights.



To make life easier, I will make some assumptions and rescaling. Assume  $b_1 > 0$ ,  $a_1 > 0$ ,  $d_1 > 0$  (not assumption)

Then we can rescale  $r, t, z$  (Amplitude, time, space) & rotate  $\theta$  in a time-dependent manner to get:

$$\begin{cases} r_t = r(1-r^2) + r_{zz} - r\theta_z^2 - \delta[2r_z\theta_z + r\theta_{zz}] \\ \theta_t = qr^2 + \theta_{zz} + \frac{2r_z\theta_z}{r} + \delta\left[\frac{r_{zz}}{r} - \theta_z^2\right] \end{cases}$$

Traveling wave w/  $r = \sqrt{1-\alpha^2}$ ,  $\theta = \Omega t + \alpha z$

$$\Omega = q(1-\alpha^2) - \delta\alpha^2 \quad (\theta_z = \alpha + \phi_z) \quad \theta_{zz} = \phi_{zz}$$

Write  $r = \sqrt{1-\alpha^2} + \rho$ ,  $\theta = \Omega t + \alpha z + \phi$  and linearize to obtain

$$\rho_t = (1-3r^2)\rho + \rho_{zz} - \rho\alpha^2 - 2r\alpha\phi_z - \delta[2\rho_z\alpha + r\phi_{zz}]$$

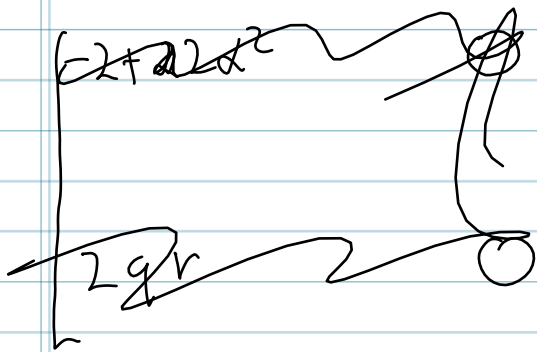
$$\phi_t = 2qr\rho + \phi_{zz} + \frac{2\alpha\rho_z}{r} + \delta\left[\frac{\rho_{zz}}{r} - 2\alpha\phi_z\right]$$

Solutions are autonomous in  $z, t$  so of the form

$$e^{\nu t + ikz} \Rightarrow \nu \begin{bmatrix} \tilde{\rho} \\ \tilde{\phi} \end{bmatrix} = \begin{bmatrix} -k^2 - \alpha^2 + 1 - 3r^2 - \delta 2ik\alpha & -2r\alpha k \\ 2qr + \frac{2\alpha ik}{r} - \frac{\delta k^2}{r} & k^2 - 2i\alpha k\delta \end{bmatrix} \begin{bmatrix} \tilde{\rho} \\ \tilde{\phi} \end{bmatrix}$$

Want eigenvalues of this complex matrix to have negative real parts for all  $k$

• ~~Let's first look at  $k=0$~~



Let's first look at small amplitude solutions. where  $\alpha \approx 1$  so that  $r$  is small

$$\begin{bmatrix} -k^2 - 2ik\delta\alpha & -2rik\alpha + \delta r k^2 \\ \frac{1}{r} [2\alpha ik - \delta k^2] & -k^2 - 2\alpha i k \delta \end{bmatrix}$$

For  $\delta = 0$  (say, diagonal diffusion)

$$\text{Tr} = -k^2 \quad \det \approx k^4 - 4\alpha^2 k^2$$

For  $k$  small, this is negative so there will be a positive eigenvalue

I won't go through details but when  $\delta = 0$  we have following result:

waves are stable iff:

$$\alpha^2 < \frac{1}{2+g^2}$$

Note  $g$  makes it worse

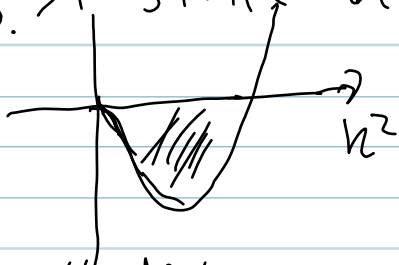
Synchronous solution.  $\alpha = 0$ ,  $r_0 = 1$

$$\begin{bmatrix} -k^2 - 2 & \delta k^2 \\ 2q - \delta k^2 & -k^2 \end{bmatrix}$$

$$\begin{aligned} \text{Det} &= k^2(2+k^2) + \delta^2 k^4 - 2q\delta k^2 \\ &= 2k^2[1 - q\delta] + k^4[1 + \delta^2] \end{aligned}$$

This is really cool if  $q\delta > 1$ . Then for  $k$  small, even synchronous solution is unstable. This is a well known instability & can lead to chaotic behavior as I will show you via numerics or that you can do yourself.

Notice this is classic pattern formula if  $q\delta > 1$  since have



We will derive another set of equations called Kuramoto-Sivashinsky, shortly.

How general is this idea?

We can replace the diffusion operator with any spatial isotropic operator. For example, consider

$$z(x) := \int_{-\infty}^{\infty} k(x-y) u(y) dy$$

we rewrite this as  $\int_{-\infty}^{\infty} k(y) u(x-y) dy$

Now suppose  $u$  depends on slow ~~time~~ <sup>space</sup>  $\varepsilon x \equiv z$ .

$$z = \int_{-\infty}^{\infty} k(y) u(z - \varepsilon y) dy \approx \int_{-\infty}^{\infty} k(y) \left[ u(z) - \varepsilon y u'(z) + \frac{\varepsilon^2 y^2}{2} u''(z) + \dots \right] dy$$

$$= k_0 u(z) + \varepsilon k_1 u'(z) + \frac{\varepsilon^2}{2} k_2 u''(z) + \dots$$

where  $k_0 = \int_{-\infty}^{\infty} k(y) dy$ ,  $k_1 = \int_{-\infty}^{\infty} y k(y) dy$ ,  $k_2 = \int_{-\infty}^{\infty} y^2 k(y) dy$

If  $k(x)$  is isotropic, then  $k_1 = 0$  & we recover the same eqns as with the reaction-diffusion model.

Now we turn to the following:

$$\frac{\partial u}{\partial t} = F(u) + D \frac{\partial^2 u}{\partial x^2} \quad -\infty < x < \infty$$

but we assume:

$\frac{du}{dt} = F(u)$  has an asymptotically stable periodic solution,  $u_0(t+T) = u_0(t)$ .

Aside F.A. alternative for periodic systems.

Consider  $\frac{dy}{dt} = A(t)y + b(t)$

and suppose  $A(t+T) = A(t)$ ,  $b(t+T) = b(t)$

Homogeneous problem:

$$\frac{dy}{dt} = A(t)y$$

Floquet Theory says solution to (1) have the form

$$y(t) \in e^{mt} P(t) \text{ where } P(t+T) = P(t)$$

Note that  $y(t+T) = e^{m(t+T)} P(t+T) = e^{mT} e^{mt} P(t) = \gamma y(t)$   
 $\gamma$  is a complex number called Floquet multiplier  
if  $\gamma = 1$  then there is a  $T$ -periodic solution to homogeneous problem (non trivial, since  $0$  is always a solution.)

This means

$$Ly \equiv \frac{dy}{dt} - A(t)y$$

has a non-trivial null space in the space of  $T$ -periodic functions. So we can solve

$$\frac{dy}{dt} - A(t)y = b(t) \quad \text{if } \int_0^T y^*(t) \cdot b(t) dt = 0$$

for every solution  $y^*(t)$  to the adjoint equation:

$$\frac{dy^*}{dt} + A^T(t)y^* = 0$$

Back to equation  $\frac{du}{dt} = F(u)$  let  $u(t) = u_0(t) + y$

$$\text{Then } \frac{dy}{dt} = A(t)y \text{ where } A(t) = D_u F(u_0(t))$$

Note  $A(t+T) = A(t)$ . Note also that  $u_0'(t)$  satisfies

$$\frac{dy}{dt} = A(t)y \quad \text{since } \frac{du_0}{dt} = F(u_0(t))$$

so

$$\frac{d^2 u_0}{dt^2} = \frac{d[u_0'(t)]}{dt} = D_u F(u_0(t)) \frac{du_0}{dt} = A(t)u_0'(t)$$

So this means that ~~the solution~~ there will be a solution to

$$\frac{dy}{dt} - D_u F(u_0(t)) y = b(t)$$

iff  $\int y^*(t) \cdot b(t) dt = 0$ , where

$$\frac{dy^*}{dt} + D_u F(u_0(t))^T y^*(t) = 0 \quad \text{XPP can compute}$$

$y^*(t)$  for you given  $u_0(t) + F(u)$ .

Note  $y^*, u_0'(t) \equiv 1$

with this in mind, we will now analyze long wave perturbations in the RD equation when there is a bulk oscillation. As above, let's suppose  $u(x,t) = u_0(t+\theta) + \varepsilon u_1 + \varepsilon^2 u_2 + \dots$

where  $\theta = \theta(\varepsilon^2 t, \varepsilon x)$  is a slowly varying phase.  $\tau = \varepsilon^2 t, \zeta = \varepsilon x$

$$\begin{aligned} \frac{\partial}{\partial t} u(x,t) &= u_0'(t+\theta) + \varepsilon^2 u_0'(t+\theta) \frac{\partial \theta}{\partial \tau} + \dots \\ \frac{\partial}{\partial x} u(x,t) &= u_0'(t+\theta) \varepsilon \frac{\partial \theta}{\partial \zeta} + \varepsilon^2 u_0'(t+\theta) \frac{\partial^2 \theta}{\partial \zeta^2} \\ \frac{\partial^2}{\partial x^2} u &= u_0''(t+\theta) \varepsilon^2 \left( \frac{\partial \theta}{\partial \zeta} \right)^2 \end{aligned}$$

So let's plug this assumption into Equations.

$$\begin{aligned} u_0' + \varepsilon u_1' + \varepsilon^2 u_2' + \varepsilon^2 u_0' \frac{\partial \theta}{\partial \tau} &= F(u_0) + \varepsilon D_u F(u_0) u_1 \\ &+ \varepsilon^2 D_u F(u_0) u_2 + \varepsilon^2 D_{uu} F(u_0) [u_1, u_1] + \dots \\ &+ \varepsilon^2 \theta_{\zeta\zeta}^2 D u_0'' + \varepsilon^2 D u_0' \theta_{\zeta\zeta} + \dots \end{aligned}$$

$u_0' = F(u_0)$  has a solution  $u_0(t+\theta)$  where  $\theta$  is an arbitrary phase

$$u_1' - A(t) u_1 = 0 \Rightarrow u_1 = 0$$

$$u_2' - A(t)u_2 = -u_0' \frac{\partial \theta}{\partial z} + D \left[ u_0'' \left( \frac{\partial \theta}{\partial z} \right)^2 + u_0' \frac{\partial^2 \theta}{\partial z^2} \right]$$

$\mathcal{M}_1$  has a solution iff outgoing to adjoint:

$$\frac{\partial \theta}{\partial z} = b \left( \frac{\partial \theta}{\partial z} \right)^2 + d \frac{\partial^2 \theta}{\partial z^2}$$

where  $b = \frac{1}{T} \int_0^T y^*(t) D u_0''(t) dt$ ,  $d = \frac{1}{T} \int_0^T y^*(t) D u_0'(t) dt$

We apply  $\mathcal{M}_1$  to solve  $\lambda - \omega$  system.

$$\begin{pmatrix} u \\ v \end{pmatrix}' = \begin{pmatrix} 1 - u^2 - v^2 & -q(u^2 + v^2) \\ q(u^2 + v^2) & 1 - u^2 - v^2 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} \quad \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} \cos qt \\ \sin qt \end{pmatrix}$$

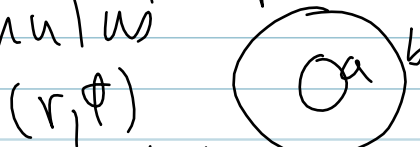
Adjoint is  $\begin{pmatrix} u^* \\ v^* \end{pmatrix} = \begin{bmatrix} \cos qt - \frac{1}{q} \sin qt \\ \sin qt + \frac{1}{q} \cos qt \end{bmatrix}$

which we leave as an exercise.

The more general form of  $\mathcal{M}_1$  equation is in  $m$  dimensions:

$$\frac{\partial \theta}{\partial z} = \alpha (\nabla \theta)^2 + \beta \nabla^2 \theta \quad *$$

Let consider the existence of rotating waves in an annulus



In polar coordinates  $(r, \phi)$  can be written

as 
$$\frac{\partial \theta}{\partial z} = \alpha \left[ \left( \frac{\partial \theta}{\partial r} \right)^2 + \frac{1}{r^2} \left( \frac{\partial \theta}{\partial \phi} \right)^2 \right] + \beta \left[ \frac{\partial^2 \theta}{\partial r^2} + \frac{1}{r} \frac{\partial \theta}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \theta}{\partial \phi^2} \right]$$

We look for rotating waves. These have the form:

$$\Theta(r, \phi, t) = \omega t - N\phi + Z(r)$$

$$\omega \text{ (the } \frac{dz}{dr} \text{ at } r=a, b = 0)$$

(For example, suppose  $Z(r)$  is just  $\alpha r$ . Then  $\omega t - N\phi + \alpha r$  defines an Archimedean spiral at each fixed time.)

Plugging this into our equation, we see that

$$\omega = \alpha \left[ \left( \frac{dz}{dr} \right)^2 + \frac{N^2}{r^2} \right] + \beta \left[ \frac{d^2 z}{dr^2} + \frac{1}{r} \frac{dz}{dr} \right]$$

$$\frac{dz}{dr}(a) = \frac{dz}{dr}(b) = 0 \quad 0 < a < b < \infty$$

If we assume  $\alpha \neq 0$  we can assume  $\alpha > 0$  wlog since we can let  $\Theta \rightarrow -\Theta$  in  $\star$ . We can ~~divide by~~ rescale space and divide by  $\alpha$  in  $\star$  to make  $\alpha, \beta = 1$  wlog.

Let  $u = dz/dr$ . Then

$$\omega = u^2 + \frac{N^2}{r^2} + u' + \frac{u}{r}$$

We want  $u(a) = u(b) = 0$

Let's see why we expect a solution of the form

$$u' + u^2 = \omega - \frac{N^2}{r^2} - \frac{u}{r}$$

Let  $u = \frac{v}{r}$ . Then

$$u' = \frac{v'}{r} - \frac{v}{r^2} \text{ so we get } \omega = \frac{v^2}{r^2} + \frac{N^2}{r^2} + \frac{v'}{r}$$



Which we rewrite as:

$$v' + \left(\frac{v}{r}\right) = r \left( \omega - \frac{N^2}{r^2} \right) \quad \text{and using an}$$

integrating factor  $e^{\int \frac{v}{r}}$  we get

$$\left( v e^{\int \frac{v}{r}} \right)' = e^{\int \frac{v}{r}} r \left( \omega - \frac{N^2}{r^2} \right)$$

So we can now get some shooting figures

Suppose  $\omega > \frac{N^2}{a^2}$ .  $V(a) = 0$  so

$$\left( v e^{\int \frac{v}{r}} \right)' > 0 \quad \text{for } r \geq a \quad \text{since } \frac{N^2}{r^2} \leq \frac{N^2}{a^2}$$

Thus  $v > 0$  for all  $r$  and we have

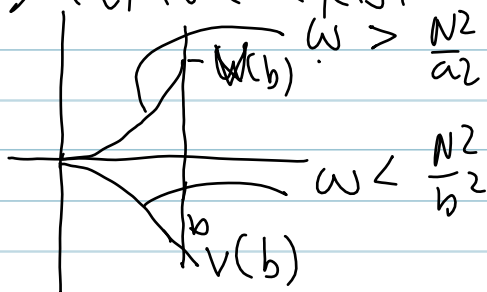


Now suppose  $\omega < \frac{N^2}{b^2}$ .

Then  $v < 0$  for all  $r$

Pick  $b$  small and greater than  $a$ .

Solution exists for  $b$  small enough



By cont wrt parameter

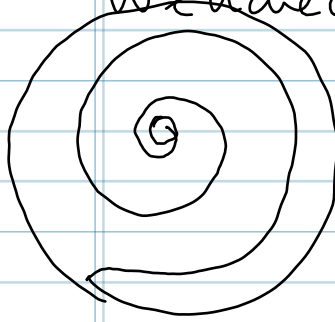
$\exists \omega$  st  $u(b) = 0$ .

Can show (with more effort), that in fact

There is an  $\omega$  st  $u(\infty) = 0$

So, in fact for all  $b$  There is a solution

We have also found that  $\omega \approx \frac{\hbar}{a^2}$  as  $a \rightarrow \infty$



Typical solution found using shooting (on computer)

### Target pattern

$$\frac{\partial Q}{\partial t} = A(\vec{r}) + \nabla^2 \theta + |\nabla \theta|^2$$

$A(\vec{r})$  is defined as follows:

$$\frac{\partial u}{\partial t} = F(u) + \varepsilon G(u, \vec{r}) + \varepsilon D \nabla^2 u$$

$$\text{Then } A(\vec{r}) = \frac{1}{T} \int_0^T u^*(t) G(u(t), \vec{r}) dt$$

Let  $\theta = \ln Q(\vec{r}, t)$ . Then (called Cole-Hopf)

$$\frac{\partial Q}{\partial t} = \frac{\partial Q}{\partial t} \frac{1}{Q} \quad \nabla Q = \frac{\nabla Q}{Q} \quad \nabla^2 \theta = -\frac{\nabla Q \cdot \nabla Q}{Q^2} + \frac{\nabla^2 Q}{Q}$$

so we get

$$\frac{\partial Q}{\partial t} = \nabla^2 Q + A(\vec{r}) Q$$

$$Q(\vec{r}, t) = e^{\lambda t} p(\vec{r}) \quad \text{we get}$$

$\lambda Q = \nabla^2 p + A(\vec{r}) p$  which is linear eigenvalue problem. Note  $\ln e^{\lambda t} \sim \lambda t$

so it's ok for  $\theta$  since it's a phase & can grow linearly in time. (and in fact, should)

Let's consider a single radially symmetric source  $A(\vec{r}) = A(r)$ . Then we get

$$\lambda P = \frac{d^2 P}{dr^2} + \frac{1}{r} \frac{dP}{dr} + A(r)P \quad \text{want } P(r) > 0$$

(since  $\theta = \ln(P) + \lambda t$ , want  $P(r)$  finite as  $r \rightarrow 0$  and  $r \rightarrow \infty$ .)

We can rewrite this as

$$\begin{aligned} \circ \left( r \frac{d^2 P}{dr^2} + \frac{dP}{dr} \right) + (r A(r) - \lambda r) P &= 0 \\ = \frac{d}{dr} \left( r \frac{dP}{dr} \right) + (r A(r) - \lambda r) P &= 0 \end{aligned}$$

With  $\frac{dP}{dr}(0) = 0$  a necessary condition.

Existence of solutions could follow from Sturm-Liouville theory but could also be found by shooting

Ex 1-dim solutions:

HW is to study inhomogeneities in finite domain

$$\theta_t = \alpha \theta_x^2 + \beta \theta_{xx}$$

Traveling wave  $\theta = \omega t - kx \Rightarrow \omega = \alpha k^2$

Are there other solutions? consider

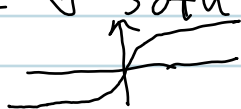
$$\theta = \omega t + q(x) \quad \text{Then}$$

$$\omega = \alpha q_x^2 + \beta q_{xx} \quad \text{Let } q_x = P$$

HW set  $\alpha = \beta = 1$

$$\omega = P^2 = P_x$$

Prove  $\exists$  solution  $P(-\infty) = -\sqrt{\omega}$ ,  $P(+\infty) = \sqrt{\omega}$  which are 1-dim targets!!



Consider an arbitrary volume  $V$  enclosed by surface  $S$



Let  $c(\vec{x}, t)$  be the concentration of some substance (could be probability or density etc)

The rate of change of "stuff" in the volume is equal to the flow into and out of the volume plus the production within the volume:

$$\frac{\partial}{\partial t} \int_V c(\vec{x}, t) dV = - \int_S \vec{J} \cdot d\vec{S} + \int_V f dV$$

Apply divergence theorem to get continuity equation:

$$\int_V \left( \frac{\partial c}{\partial t} + \nabla \cdot \vec{J} - f \right) dV = 0$$

Since  $V$  is arbitrary:

$$\boxed{\frac{\partial c}{\partial t} + \nabla \cdot \vec{J} - f = 0}$$

$$\frac{\partial c}{\partial t} = f + \nabla \cdot (D \nabla c)$$

get standard equation.

Diffusion

$$\vec{J} = -D \nabla c$$

+ we get

IF  $D$  is constant  
Then pull it out to  
more crowded  
more persal  
d(x) persal

We have already studied this in detail.

Some models for animal dispersal have  $D$  dependent on  $n$ , eg  $D(n) = D_0 \left( \frac{n}{n_0} \right)^m$  where  $n$  is density of animals

Pure dispersal: <sup>of insects</sup> in one dimension:

$$\frac{\partial n}{\partial t} = D_0 \frac{\partial}{\partial x} \left( \left( \frac{n}{n_0} \right)^m \frac{\partial n}{\partial x} \right)$$

$$n(x,t) = \begin{cases} \frac{n_0}{\lambda(t)} \left[ 1 - \left\{ \frac{x}{r_0 \lambda(t)} \right\}^2 \right]^{1/m} & |x| \leq r_0 \lambda(t) \\ 0 & |x| > r_0 \lambda(t) \end{cases}$$

$$\lambda(t) = \left( \frac{t}{t_0} \right)^{\frac{1}{2+m}} \quad r_0 = \frac{Q \Gamma\left(\frac{1}{m} + \frac{3}{2}\right)}{\left\{ \pi^{\frac{1}{2}} n_0 \Gamma\left(\frac{1}{m} + 1\right) \right\}}$$

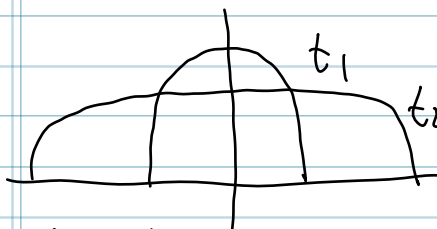
$$t_0 = \frac{r_0^2 m}{2D_0}$$

You can check that this is a solution. Interesting question: ask what happens as  $m \rightarrow 0$ .  $Q = n(0,0)$

$r_0$  is from requirement (conservation of insects)

Recall pure diffusion:  $n(x,t) = \frac{Q}{2(\pi D t)^{1/2}} e^{-\frac{x^2}{4Dt}}$

In pure diffusion at any finite  $t > 0$ ,  $n(x,t) > 0$  for all  $x$  - instant communication. Here it is finite speed. ~~rather~~ (this is also porous medium equation)



can solve this in radial coordinates as well

At low pops, insects tend to aggregate so might have negative diffusion at low pops

$$J = un - D(n) \frac{\partial n}{\partial x}$$

$u = -u_0 \operatorname{sgn}(x)$  where origin is point of aggregation

At steady state  $n(x,t) \rightarrow n(x)$

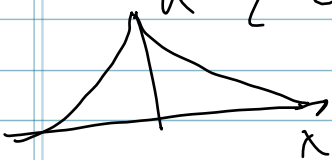
$$0 = u_0 \frac{d}{dx} [n \operatorname{sgn}(x)] + D_0 \frac{d}{dx} \left[ \left( \frac{n}{n_0} \right)^m \frac{dn}{dx} \right]$$

integrate (Need  $n(x) \rightarrow 0$  as  $x \rightarrow \pm \infty$  so

$$0 = u_0 n \operatorname{sgn}(x) + D_0 \left( \frac{n}{n_0} \right)^m \frac{dn}{dx}$$

~~Take  $x > 0$~~  solve this is an easy exercise

$$n(x) = \begin{cases} n_0 \left( 1 - \frac{u_0 |x|}{D_0} \right)^{1/m} & |x| \leq \frac{D_0}{u_0} \\ 0 & |x| > \frac{D_0}{u_0} \end{cases}$$



Chemotaxis. Let  $a(x,t)$  be an attractant in chemotaxis organisms, move up or down according to the gradient of  $a(x,t)$ ,  $\nabla a$ , seeking a maximum (attract) or a minimum (repulse)

so that  $J_c = n \chi(a) \nabla a$   $\chi$  is called the chemotactic constant.  $J_{\text{total}} = J_{\text{diff}} + J_{\text{chem}}$

$$\frac{dn}{dt} = \underbrace{f(n)}_{\text{growth}} - \underbrace{\nabla(n \chi(a) \nabla a)}_{\text{chemo}} + \underbrace{\nabla(D_0 \nabla n)}_{\text{diff}}$$

Typically  $a$  has dynamics as well:

$$\frac{da}{dt} = g(a,n) + \nabla(D_a \nabla a)$$

Keller-Segel equations,  $g = hn - ka$  and  $f=0$

we will make a model of axon growth & guidance, for patterns in which neurites.

Let  $n(x,t) \equiv \#$  thalassoid cortical axons in a barrel. We assume neural random motion, growth, pruning, & chemotactic attraction:

$$\begin{cases} \frac{\partial n}{\partial t} = \alpha_0 - \alpha_1 n + D_n \nabla^2 n - \chi \nabla n \cdot \nabla c \\ \frac{\partial c}{\partial t} = f(n) - \alpha_2 c + D_c \nabla^2 c \end{cases} \quad \text{in } \Omega \subset \mathbb{R}^2$$

$\nabla n = \nabla c = 0$  on  $\partial \Omega$ .  $f'(n) > 0$  (KS (f(n) = hn))

Equilibria:  $\bar{n} = \frac{\alpha_0}{\alpha_1}$ ,  $\bar{c} = \frac{1}{\alpha_2} f\left(\frac{\alpha_0}{\alpha_1}\right)$

Stability:

$$\frac{\partial u}{\partial t} = -\alpha_1 u + D_n \nabla^2 u - \chi \bar{n} \nabla^2 c$$

$$\frac{\partial c}{\partial t} = f'(\bar{n}) \alpha_2 u + D_c \nabla^2 c$$

Let  $-k^2$  be eigenvalue of  $\nabla^2$  on  $\Omega$   $\nabla^2 u = -k^2 u$

Then  $(n, c) = (n_0, c_0) e^{\lambda t} u(\bar{x})$  and:

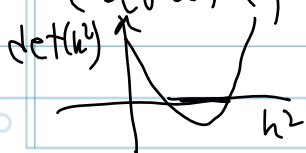
$$\lambda \begin{bmatrix} n_0 \\ c_0 \end{bmatrix} = \begin{bmatrix} -\alpha_1 - D_n k^2 & \chi \bar{n} k^2 \\ f'(\bar{n}) & -\alpha_2 - D_c k^2 \end{bmatrix} \begin{bmatrix} n_0 \\ c_0 \end{bmatrix}$$

Trace =  $-\alpha_1 - \alpha_2 - (D_n + D_c) k^2 < 0$

det  $\stackrel{(k^2)}{=} \alpha_1 \alpha_2 + (\alpha_1 D_n \alpha_2 D_c) k^2 + D_n D_c k^4 - \chi \bar{n} f'(n) k^2$

Clearly det  $> 0$  at  $k=0$  det  $> 0$  for  $k$  large.

But for  $k$  in between, if  $\chi f'(n)$  is large enough, then can get pattern formation!



"Cross between"

## Example 2 Predator prey runaway

prey  $\frac{\partial u}{\partial t} = f(u, v) + D_u \nabla^2 u + \chi_u \nabla \cdot (u \nabla v)$

pred  $\frac{\partial v}{\partial t} = g(u, v) + D_v \nabla^2 v - \chi_v \nabla \cdot (v \nabla u) \leftarrow \text{chase}$

Simplest possible case  $f(u, v) = a u (1 - u - b v)$

$$g(u, v) = c v (-1 + d u)$$

For simplicity take  $a = c = 1$ ,  $d = \frac{1}{2}$ ,  $b = 1$

So  $u = v = \frac{1}{2}$  is coexistent state

Linearization:

$$\frac{\partial u}{\partial t} = \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2} \\ 1 & 0 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} + \begin{bmatrix} D_u & \frac{\chi_u}{2} \\ -\frac{\chi_v}{2} & D_v \end{bmatrix} \nabla^2 \begin{bmatrix} u \\ v \end{bmatrix}$$

$$\begin{bmatrix} -\frac{1}{2} - D_u k^2 & -\frac{1}{2} - \frac{\chi_u}{2} k^2 \\ 1 + \frac{\chi_v}{2} k^2 & -D_v k^2 \end{bmatrix} \quad \text{tr} = -\frac{1}{2} - (D_u + D_v) k^2$$

$$\det = \left(\frac{1}{2} + D_u k^2\right) D_v k^2 - \left(\frac{1}{2} + \frac{\chi_u}{2} k^2\right) \left(1 + \frac{\chi_v}{2} k^2\right)$$

No pattern formation

Did I make a mistake.



### Example 3 Pattern in *Bacillus subtilis*.

If *B. subtilis* is inoculated onto agar with very little nutrient, it can exhibit very

cool patterns. Let  $n(x,t)$  be nutrient and let  $b(x,t)$  be bacteria concentration.

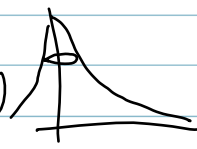
$$\frac{\partial n}{\partial t} = D_n \nabla^2 n - \frac{knb}{1+\gamma n} \quad \left( \text{consumption of nutrient} \right)$$

$$\frac{\partial b}{\partial t} = \nabla \cdot (D_b \nabla b) + \theta \frac{knb}{1+\gamma n} \quad \left( \begin{array}{l} \text{growth rate} \\ \text{of bacteria from} \\ \text{nutrient} \end{array} \right)$$

Experimentally it is found that bacteria tend to move very little when nutrient is low at core of colony + also very little at edge where density of bacteria is low. so they suggest

$$D_b = \sigma n b$$

They also supposed  $\sigma = 1 + \Delta$  where  $\Delta$  is random fluctuation of movement.

Initial data  $n(x,0) = n_0$ ,  $b(x,0) = b_0(x)$  

can rescale the equation as

$$n^* = \left( \frac{\theta}{D_n} \right)^{1/2} n \quad b^* = \left( \frac{1}{\theta D_n} \right)^{1/2} b \quad \gamma^* = \left( \frac{D_n}{\theta} \right)^{1/2} \gamma$$

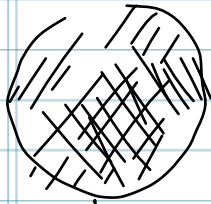
$$t^* = k (\theta D_n)^{1/2} t \quad x^* = \left( \frac{\theta k^2}{D_n} \right)^{1/4} x \quad \text{to get}$$

simpler model + then set  $\gamma = 0$  since  $n$  is pretty low.

$$\frac{\partial n}{\partial t} = \nabla^2 n - n b \quad \frac{\partial b}{\partial t} = \nabla \cdot (\sigma n b \nabla b) + n b$$

$\sigma$  + initial data are only parameters

Some examples



uniform  
 $\sigma_0 = 4$   
 $\nu_0$  (initial Food) = 1.07



complex branched Fractal  
 $\sigma = 1, \nu = 1.35$

colony growth approximation. Tips moving out at some rate  
 consider  $\frac{dn}{dt} = -nb$   $\frac{db}{dt} = bn \sim n+b \equiv \text{constant}$

so  $\frac{dn}{dt} \approx b(1 - \frac{b}{n})$  so Maximum of  $n$  is paper approximation

$$\frac{db}{dt} = \nu_0 b(1 - \frac{b}{n}) + \frac{\partial}{\partial x} \left[ \sigma \nu_0 b \frac{\partial b}{\partial x} \right] \quad \nu_0 = 1 \text{ w/o } c \text{ (rescue time)}$$

Let's look for traveling waves.  $b(x,t) = U(z)$  rescale  $b/\nu$   
 $z = x - ct$

$$-c \frac{db}{dz} = b(1-b) + \sigma \frac{d}{dz} \left( b \frac{db}{dz} \right)$$

$$U(+\infty) = 0 \quad U(-\infty) = 1$$



$$b \frac{db}{dz} = a$$

$$\sigma b \frac{da}{dz} = -c a - b^2(1-b)$$

$$\sigma \frac{da}{db} = \frac{-ca - b^2(1-b)}{a}$$

(can solve this) by shooting

Find 3 waves if  $c$  is large enough

For the present problem  
 $c \approx \left( \frac{\sigma_0 v_0^3}{2} \right)^{1/2}$  .

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