

Uniform inf-sup condition for the Brinkman problem in highly heterogeneous media

Raytcho Lazarov & Aziz Takhirov

Texas A&M

May 3-4, 2016

- 1 Outline
- 2 Motivation
- 3 Related work
- 4 The continuous problem
- 5 The discrete problem
- 6 References

Brinkman equation

$$\begin{aligned} -\tilde{\nu}\Delta\mathbf{u} + \nu K^{-1}\mathbf{u} + \nabla p &= \mathbf{f} \text{ in } \Omega, \\ \nabla \cdot \mathbf{u} &= 0 \text{ in } \Omega, \\ \mathbf{u} &= 0 \text{ on } \partial\Omega, \end{aligned}$$

where

- \mathbf{u} is the fluid velocity.
- p is the pressure.
- ν is the viscosity. We assume $\nu = 1$.
- $\tilde{\nu}$ is the effective viscosity. We assume $\tilde{\nu} = 1$.
- \mathbf{f} is the external forcing term.
- $0 < K(x) < \infty$ is the permeability of the medium.

Brinkman equation

Brinkman can be used to model flows in:

- Pebble Bed Reactors,
- filtration,
- biological flows,
- oil/water reservoirs.

Flows in highly heterogeneous media

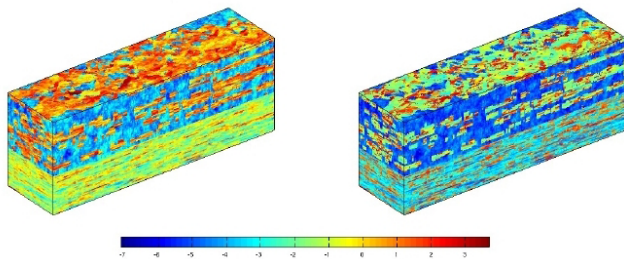


Figure: SPE10 3 dimensional permeability distributions, logscale.

Flows in highly heterogeneous media

- When permeability field $K(x)$ has large variations and jumps, the problem becomes more challenging.
- Contrast of the media: $\kappa_{\Omega} = \frac{\max_{x \in \Omega} K(x)}{\min_{x \in \Omega} K(x)}$.
- Exact solution has low regularity when $\kappa_{\Omega} \gg 1$.
- The known iterative methods, converge very slowly or practically do not converge when $\kappa_{\Omega} \gg 1$, due to the dependence of the condition number of the linear system on κ_{Ω} .

Preconditioners

- X - real, separable, Hilbert space,
- inner product on X is (\cdot, \cdot) , norm on X is $\|\cdot\|$,
- X^* be the dual of X , $\langle \cdot, \cdot \rangle$ be the duality pairing.

Given $\mathcal{A} \in \mathcal{L}(X, X^*)$, symmetric and $f \in X^*$, find $x \in X$ such that

$$\mathcal{A}x = f \Leftrightarrow$$

$$a(x, y) := \langle \mathcal{A}x, y \rangle = \langle f, y \rangle \quad \forall y \in X.$$

Preconditioners cont-d

Definition

[3, Mardal & Winther (2011)] $\mathcal{B} \in \mathcal{L}(X^*, X)$ is a preconditioner for $\mathcal{A} \in \mathcal{L}(X, X^*)$ if \mathcal{B} is symmetric and positive definite in the sense that

$$\langle \cdot, \mathcal{B} \cdot \rangle$$

is inner product on X^* .

\mathcal{B} is a Riesz operator: Given $f \in X^*$

$$(\mathcal{B}f, y) = \langle f, y \rangle \quad \forall y \in X.$$

Preconditioned system

Usually

$$\mathcal{A}x = f$$

is preconditioned as

$$\mathcal{B}\mathcal{A}x = \mathcal{B}f.$$

Condition number of the system

$$\text{cond}(\mathcal{B}\mathcal{A}) := \|\mathcal{B}\mathcal{A}\|_{\mathcal{L}(X,X)} \|(\mathcal{B}\mathcal{A})^{-1}\|_{\mathcal{L}(X,X)}$$

Letting

$$\|a\| := \sup_{x,y \in X} \frac{a(x,y)}{\|x\|\|y\|}, \quad \inf_{x \in X} \sup_{y \in Y} \frac{a(x,y)}{\|x\|\|y\|} \geq \gamma \Rightarrow$$

$$\text{cond}(\mathcal{B}\mathcal{A}) \leq \frac{\|a\|}{\gamma}.$$

Condition number of the Brinkman problem

Let

$$\mathcal{A} = \begin{pmatrix} -\Delta + \mathcal{I}K^{-1} & \nabla \\ -\nabla \cdot & 0 \end{pmatrix}.$$

Brinkman system:

$$\mathcal{A} \begin{pmatrix} \mathbf{u} \\ p \end{pmatrix} = \begin{pmatrix} \mathbf{f} \\ 0 \end{pmatrix}.$$

If $X = (H_0^1, \|\nabla \cdot \|)$, $Q = (L_0^2, \|\cdot \|)$, then

$$\mathcal{B} = \begin{pmatrix} (-\Delta)^{-1} & 0 \\ 0 & \mathcal{I} \end{pmatrix}.$$

Condition number of the system

$$\text{cond}(\mathcal{B}\mathcal{A}) \leq \mathcal{O}(\kappa_\Omega).$$

Question

Is it possible to establish well-posedness of the Brinkman problem, such that $\text{cond}(\mathcal{BA})$ is independent of the media contrast κ_Ω ?

Singularly perturbed Stokes system

In [2, Mardal & Winther (2004)], authors consider

$$\begin{aligned} -\varepsilon \Delta \mathbf{u} + \mathbf{u} + \nabla p &= \mathbf{f} \text{ in } \Omega, \\ \nabla \cdot \mathbf{u} &= 0 \text{ in } \Omega, \\ \mathbf{u} &= 0 \text{ on } \partial\Omega. \end{aligned}$$

Authors establish well-posedness in ε -dependent norms, both in continuous and discrete cases.

Intersection and sum of Hilbert spaces

If X and Y are Hilbert spaces, then $X + Y$ and $X \cap Y$ are also Hilbert spaces [1, Bergh, Löfström], with the following norms:

$$\|z\|_{X \cap Y} = \sqrt{\|z\|_X^2 + \|z\|_Y^2} \sim \max(\|z\|_X, \|z\|_Y),$$

$$\|z\|_{X+Y} = \inf_{\substack{z=x+y \\ x \in X, y \in Y}} \sqrt{\|x\|_X^2 + \|y\|_Y^2}.$$

If $X \cap Y$ is dense in both X and Y , then

$$(X \cap Y)^* = X^* + Y^*, \text{ and } (X + Y)^* = X^* \cap Y^*.$$

The continuous, weak formulation

$$\begin{aligned} a(\mathbf{u}, \mathbf{v}) + b(p, \mathbf{v}) &= (\mathbf{f}, \mathbf{v}) \\ b(q, \mathbf{u}) &= 0, \end{aligned}$$

$$\begin{aligned} a(\mathbf{u}, \mathbf{v}) &:= (\nabla \mathbf{u}, \nabla \mathbf{v}) + (\mathbf{u}, \mathbf{v})_{\alpha}, \\ b(p, \mathbf{v}) &:= (p, \nabla \cdot \mathbf{v}), \end{aligned}$$

where $\alpha = K^{-1}$.

The natural space for the velocity field is

$$X := (H_0^1 \cap L_{\alpha}^2)^d, \quad \|\mathbf{u}\|_X := \sqrt{\|\nabla \mathbf{u}\|^2 + \|\mathbf{u}\|_{\alpha}^2}.$$

The pressure norm

$\|\cdot\|_Q$ should be chosen, so that the Brezzi theory for well posedness holds:

- $a(\mathbf{u}, \mathbf{v}) \leq \|a\| \|\mathbf{u}\|_X \|\mathbf{v}\|_X,$
- $a(\mathbf{u}, \mathbf{u}) \geq a_0 \|\mathbf{u}\|_X^2,$
- $b(p, \mathbf{v}) \leq \|b\| \|p\|_Q \|\mathbf{v}\|_X,$
- $\inf_{p \in Q} \sup_{\mathbf{v} \in X} \frac{b(p, \mathbf{v})}{\|p\|_Q \|\mathbf{v}\|_X} \geq \beta.$

For our applications, we need to ensure that $\text{cond}(\mathcal{BA})$ is independent of κ_Ω .

The pressure norm

Let

$$Q := L_0^2 + H_K^1 \cap L_0^2 = \{q \in L_0^2 : q = q_1 + q_2, q_1 \in L_0^2, q_2 \in H_K^1 \cap L_0^2\},$$

with the associated norm

$$\|q\|_Q = \inf_{\substack{q=q_1+q_2 \\ q_1 \in L_0^2, q_2 \in H_K^1 \cap L_0^2}} \sqrt{\|q_1\|^2 + \|\nabla q_2\|_K^2}.$$

The pressure norm

Lemma

Given $q \in L_0^2$, let $q_2 \in H_K^1 \cap L_0^2$ be the solution of the following elliptic problem:

$$\begin{cases} -\nabla \cdot (K \nabla q_2) + q_2 = q \text{ in } \Omega, \\ K \nabla q_2 \cdot \mathbf{n} = 0 \text{ on } \partial\Omega. \end{cases}$$

Then

$$\begin{aligned} \|q\|_{L_0^2 + H_K^1 \cap L_0^2} &= \sqrt{\|q_1\|^2 + \|\nabla q_2\|_K^2} \\ &= \sqrt{\|q - q_2\|^2 + \|\nabla q_2\|_K^2} \\ &= \sqrt{\|q\|^2 - \|q_2\|_{H_K^1 \cap L_0^2}^2}. \end{aligned}$$

Well-posedness: Continuity of $b(\cdot, \cdot)$

Lemma

The bilinear form $b(\cdot, \cdot) : Q \times X \rightarrow R$ is continuous.

Proof.

$\forall q \in Q$, let $q = q_1 + q_2$ with $q_1 \in L_0^2$ and $q_2 \in H_K^1 \cap L_0^2$. Then

$$\begin{aligned}
 b(q, \mathbf{v}) &= b(q_1, \mathbf{v}) + b(q_2, \mathbf{v}) \\
 &= -(q_1, \nabla \cdot \mathbf{v}) + (\nabla q_2, \mathbf{v}) \\
 &= -(q_1, \nabla \cdot \mathbf{v}) + \left(K^{\frac{1}{2}} \nabla q_2, \alpha^{\frac{1}{2}} \mathbf{v} \right) \\
 &\leq \sqrt{d} \|q_1\| \|\nabla \mathbf{v}\| + \|\nabla q_2\|_K \|\mathbf{v}\|_\alpha \\
 &\leq \sqrt{d} \sqrt{\|q_1\|^2 + \|\nabla q_2\|_K^2} \|\mathbf{v}\|_X.
 \end{aligned}$$

Taking infimum over all q_1, q_2 gives $b(q, \mathbf{v}) \leq \sqrt{d} \|q\|_Q \|\mathbf{v}\|_X$.

Well-posedness: Coercivity of $b(\cdot, \cdot)$

Lemma

There exists a constant $\beta > 0$, independent of $0 < K(x) < \infty$, such that

$$\inf_{q \in Q} \sup_{\mathbf{v} \in X} \frac{b(q, \mathbf{v})}{\|q\|_Q \|\mathbf{v}\|_X} \geq \beta.$$

Proof of the coercivity of $b(\cdot, \cdot)$

Proof.

The result of Nečas: $\forall q \in L_0^2(\Omega) : \|\nabla q\|_{H^{-1}(\Omega)} \sim \|q\|$.

$\forall q \in Q$ with $q = q_1 + q_2$ and $\int_{\Omega} q_i = 0$. Assuming that the duality pairing

$\langle \cdot, \cdot \rangle_{X^* \times X}$ is an extension of the L^2 inner product, one obtains that:

$$\begin{aligned} \sup_{\mathbf{v} \in X} \frac{b(q, \mathbf{v})}{\|\mathbf{v}\|_X} &= \|\nabla q\|_{X^*} = \|\nabla q\|_{H^{-1} + L_K^2} \\ &= \inf_{\substack{q = q_1 + q_2 \\ \nabla q_1 \in H^{-1}, \nabla q_2 \in L_K^2}} \sqrt{\|\nabla q_1\|_{H^{-1}}^2 + \|\nabla q_2\|_K^2} \\ &\geq C \inf_{\substack{q = q_1 + q_2 \\ q_1 \in L_0^2, q_2 \in H_K^1 \cap L_0^2}} \sqrt{\|q_1\|^2 + \|\nabla q_2\|_K^2} \\ &= C \|q\|_Q. \end{aligned}$$

Assumption

Assumption. The mesh has resolved the heterogeneity of the medium so that elementwise contrast

$$\kappa_E = \frac{\max_{x \in E} K(x)}{\min_{x \in E} K(x)}$$

is a moderate constant. We will also set

$$\kappa_{\mathcal{T}_h} = \max_{E \in \mathcal{T}_h} \kappa_E.$$

Inf-sup with conforming subspaces

Fortin's Lemma for Mini-element:

- $\Pi_h = \Pi_h^b (I - C_h) + C_h$.
- Π_h^b satisfies $(\nabla \cdot \Pi_h^b \mathbf{v}, q_h) = (\nabla \cdot \mathbf{v}, q_h)$.
- C_h is Clement or Scott-Zhang (quasilocal) interpolant.
- In particular need, $\|C_h \mathbf{v}\|_\alpha \leq c \|\mathbf{v}\|_\alpha$, with c independent of κ_Ω .

For any $E \in \mathcal{T}_h$:

$$\begin{aligned} \|C_h \mathbf{v}\|_{\alpha, E}^2 &\leq \max_{x \in E} \alpha(x) \|C_h \mathbf{v}\|_E^2 \leq C \max_{x \in E} \alpha(x) \|\mathbf{v}\|_{\Omega_E}^2 \\ &\leq C \frac{\max_{x \in E} \alpha(x)}{\min_{x \in \Omega_E} \alpha(x)} \|\mathbf{v}\|_{\alpha, \Omega_E}^2. \end{aligned}$$

Non-conforming velocity space

$$X_h := \left(P_k^d \oplus \mathbf{x}P_k \right) \cap H_0(\operatorname{div}, \Omega), \quad Q_h := P_{k-1} \subset H^1(\Omega).$$

$$J(\mathbf{u}_h, \mathbf{v}_h) := \sum_{e \in \Gamma_h \cup \Gamma} \frac{\sigma_e}{|e|} \int_e [\mathbf{u}_h][\mathbf{v}_h],$$

$$\begin{aligned} a_h(\mathbf{u}_h, \mathbf{v}_h) &:= \sum_{E \in \mathcal{T}_h} (\nabla \mathbf{u}_h, \nabla \mathbf{v}_h)_E + (\alpha \mathbf{u}_h, \mathbf{v}_h) + J(\mathbf{u}_h, \mathbf{v}_h) \\ &\quad - \sum_{e \in \Gamma_h \cup \Gamma} \int_e \{\nabla \mathbf{u}_h \cdot \mathbf{n}\} [\mathbf{v}_h] - \sum_{e \in \Gamma_h \cup \Gamma} \int_e \{\nabla \mathbf{v}_h \cdot \mathbf{n}\} [\mathbf{u}_h], \end{aligned}$$

$$b_h(p_h, \mathbf{v}_h) := - \sum_{E \in \mathcal{T}_h} (p_h, \nabla \cdot \mathbf{v}_h)_E$$

Discrete weak formulation

$$a_h(\mathbf{u}_h, \mathbf{v}_h) + b_h(p_h, \mathbf{v}_h) = (\mathbf{f}, \mathbf{v}_h)$$

$$b_h(q_h, \mathbf{u}_h) = 0.$$

$$\|\mathbf{u}_h\|_{X_h} := \sqrt{\sum_{E \in \mathcal{T}_h} \|\nabla \mathbf{u}_h\|_E^2 + \|\mathbf{u}_h\|_\alpha^2 + J(\mathbf{u}_h, \mathbf{u}_h)},$$

$$\|q_h\|_Q := \inf_{q_h = q_1 + q_2} \sqrt{\|q_1\|^2 + \|\nabla q_2\|_K^2} = \sqrt{\|q_h - q_2\|^2 + \|\nabla q_2\|_K^2}.$$

Discrete inf-sup

Lemma

The following inf-sup condition holds: There exists a constant $\beta_h > 0$, independent of κ_Ω and h , such that

$$\inf_{q_h \in Q_h} \sup_{\mathbf{v}_h \in X_h} \frac{b_h(q_h, \mathbf{v}_h)}{\|q_h\|_Q \|\mathbf{v}_h\|_{X_h}} \geq \beta_h.$$

Proof of discrete inf-sup

Proof.

Let $\forall q_h \in Q_h$. By continuous inf-sup condition, there exists $\mathbf{v} \in X$ such that

$$b(q_h, \mathbf{v}) \geq \beta \|q_h\|_Q \|\mathbf{v}\|_X.$$

Let $\mathbf{v}_h = \pi_h \mathbf{v} \in X_h$ be the Raviart-Thomas interpolant of \mathbf{v} . By definition of the Raviart-Thomas interpolant:

$$\begin{aligned} b_h(q_h, \mathbf{v}_h) &= - \sum_{E \in \mathcal{T}_h} (\nabla \cdot \mathbf{v}_h, q_h)_E = - \sum_{E \in \mathcal{T}_h} (\nabla \cdot \mathbf{v}, q_h)_E \\ &= b(q_h, \mathbf{v}) \geq \beta \|q_h\|_Q \|\mathbf{v}\|_X. \end{aligned}$$

One can show that

$$\|\mathbf{v}_h\|_\alpha \leq C \kappa_{\mathcal{T}_h} \|\mathbf{v}\|_\alpha \Rightarrow \|\mathbf{v}_h\|_X \leq C(\kappa_{\mathcal{T}_h}) \|\mathbf{v}\|_X.$$

Continuous vs. discrete pressure norms

Recall that for $p_h \in L_0^2$,

$$\|p_h\|_Q = \sqrt{\|p_h\|^2 - \|p_2\|_{H_K^1 \cap L_0^2}^2},$$

where

$$(K \nabla p_2, \nabla q) + (p_2, q) = (p_h, q) \quad \forall q \in H_K^1 \cap L_0^2.$$

So in general, $p_2 \notin Q_h$, and therefore $\|p_h\|_Q$ is not computable.

Continuous vs. discrete pressure norms

Let

$$\|p_h\|_{Q_h} = \sqrt{\|p_h\|^2 - \|p_{2,h}\|_{H_K^1 \cap L_0^2}^2},$$

where

$$(K \nabla p_{2,h}, \nabla q_h) + (p_{2,h}, q_h) = (p_h, q_h) \quad \forall q_h \in Q_h,$$




Then

$$\begin{aligned} \|p_{2,h}\|_{H_K^1 \cap L_0^2} &\leq \|p_2\|_{H_K^1 \cap L_0^2} \Rightarrow \\ \|p_h\|_{Q_h} &\geq \|p_h\|_Q. \end{aligned}$$

The end

THANK YOU!

References

-  J. Bergh, J. Löfström, *Interpolation Spaces: An Introduction*, Springer Berlin Heidelberg, 1976.
-  K-A Mardal, R. Winther, *Uniform preconditioners for the time dependent Stokes problem*, Numerische Mathematik 98 (2), 305-327.
-  K-A Mardal, R. Winther, *Preconditioning discretizations of systems of partial differential equations*, Numer. Linear Algebra Appl. (18) 2011, 1-40.